

Linear maps

Bioinformatics Degree
Algebra

Departament de Matemàtiques



Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the zero map.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity* map Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the zero map.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity* map Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Definition

A **linear map** (or linear transformation) between \mathbb{R}^n and \mathbb{R}^m is a map that preserves linear combinations. More precisely,

Definition

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear map** if

1. $f(u + v) = f(u) + f(v)$ for all $u, v \in \mathbb{R}^n$, and
2. $f(cv) = cf(v)$ for any $c \in \mathbb{R}$ and any $v \in \mathbb{R}^n$.

Examples

- ▶ $f(x) = 5x$
- ▶ $f(x, y) = (x + 2y, 3x, y - x)$
- ▶ $f(x, y, z) = x - 3y + z$
- ▶ $f(x, y, z) = (x, 2y, z)$
- ▶ $f(x_1, \dots, x_n) = (0, \dots, 0)$ is the *zero map*.
- ▶ $f(x_1, \dots, x_n) = (x_1, \dots, x_n)$ is the *identity map* Id .

Properties of linear maps

If f is a linear map, then:

- ▶ $f(0) = 0$
- ▶ $f(c_1 v_1 + \cdots + c_k v_k) = c_1 f(v_1) + \cdots + c_k f(v_k)$. This is equivalent to properties 1 and 2.
- ▶ f is determined by the image of a basis.

Properties of linear maps

If f is a linear map, then:

- ▶ $f(0) = 0$
- ▶ $f(c_1 v_1 + \cdots + c_k v_k) = c_1 f(v_1) + \cdots + c_k f(v_k)$. This is equivalent to properties 1 and 2.
- ▶ f is determined by the image of a basis.

Properties of linear maps

If f is a linear map, then:

- ▶ $f(0) = 0$
- ▶ $f(c_1 v_1 + \cdots + c_k v_k) = c_1 f(v_1) + \cdots + c_k f(v_k)$. This is equivalent to properties 1 and 2.
- ▶ f is determined by the **image of a basis**.

Standard matrix of a linear map

When we use coordinates in the standard bases, then linear maps

$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$(x_1, \dots, x_n) \mapsto (a_{11}x_1 + \dots + a_{1n}x_n, \dots, a_{m1}x_1 + \dots + a_{mn}x_n)$$

can be written in matrix notation as follows:

$$u \mapsto M(f)u, \text{ where } M(f) = (a_{i,j}).$$

The matrix $M(f)$ is called the **standard matrix** of the linear map f . It is a $m \times n$ matrix, and its columns are the vectors $f(e_i)$, $i = 1, \dots, n$:

$$M(f) = (f(e_1), \dots, f(e_n))$$

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Definitions

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a map.

- ▶ f is **injective** if different vectors always have different images ($u \neq v$ implies $f(u) \neq f(v)$).
- ▶ f is **surjective** if every vector v in \mathbb{R}^m is the image of some vector $u \in \mathbb{R}^n$, $v = f(u)$.
- ▶ f is **bijective** if it is at the same time injective and surjective. A bijective linear map is called an *isomorphism*.

Definitions

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a map.

- ▶ f is **injective** if different vectors always have different images ($u \neq v$ implies $f(u) \neq f(v)$).
- ▶ f is **surjective** if every vector v in \mathbb{R}^m is the image of some vector $u \in \mathbb{R}^n$, $v = f(u)$.
- ▶ f is **bijective** if it is at the same time injective and surjective. A bijective linear map is called an *isomorphism*.

Definitions

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a map.

- ▶ f is **injective** if different vectors always have different images ($u \neq v$ implies $f(u) \neq f(v)$).
- ▶ f is **surjective** if every vector v in \mathbb{R}^m is the image of some vector $u \in \mathbb{R}^n$, $v = f(u)$.
- ▶ f is **bijective** if it is at the same time injective and surjective. A bijective linear map is called an *isomorphism*.

Null space of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **null space** (or **kernel**) of a f is the subspace

$$\text{Null}(f) = \{v \in \mathbb{R}^n \mid f(v) = 0\} = \{x \in \mathbb{R}^n \mid Ax = 0\} = f^{-1}(0).$$

The null space of f is the solution space of the homogeneous linear system $M(f)x = 0$. Hence, $\dim \text{Null}(f) = n - \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is injective;
2. $\text{Null}(f) = \{0\}$;
3. $\text{rank}(M(f)) = n$.

Null space of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **null space** (or **kernel**) of a f is the subspace

$$\text{Null}(f) = \{v \in \mathbb{R}^n \mid f(v) = 0\} = \{x \in \mathbb{R}^n \mid Ax = 0\} = f^{-1}(0).$$

The null space of f is the solution space of the homogeneous linear system $M(f)x = 0$. Hence, $\dim \text{Null}(f) = n - \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is injective;
2. $\text{Null}(f) = 0$;
3. $\text{rank}(M(f)) = n$.

Null space of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **null space** (or **kernel**) of a f is the subspace

$$\text{Null}(f) = \{v \in \mathbb{R}^n \mid f(v) = 0\} = \{x \in \mathbb{R}^n \mid Ax = 0\} = f^{-1}(0).$$

The null space of f is the solution space of the homogeneous linear system $M(f)x = 0$. Hence, $\dim \text{Null}(f) = n - \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is injective;
2. $\text{Null}(f) = 0$;
3. $\text{rank}(M(f)) = n$.

Null space of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **null space** (or **kernel**) of a f is the subspace

$$\text{Null}(f) = \{v \in \mathbb{R}^n \mid f(v) = 0\} = \{x \in \mathbb{R}^n \mid Ax = 0\} = f^{-1}(0).$$

The null space of f is the solution space of the homogeneous linear system $M(f)x = 0$. Hence, $\dim \text{Null}(f) = n - \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is injective;
2. $\text{Null}(f) = 0$;
3. $\text{rank}(M(f)) = n$.

Null space of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **null space** (or **kernel**) of a f is the subspace

$$\text{Null}(f) = \{v \in \mathbb{R}^n \mid f(v) = 0\} = \{x \in \mathbb{R}^n \mid Ax = 0\} = f^{-1}(0).$$

The null space of f is the solution space of the homogeneous linear system $M(f)x = 0$. Hence, $\dim \text{Null}(f) = n - \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is injective;
2. $\text{Null}(f) = 0$;
3. $\text{rank}(M(f)) = n$.

Range of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **range** (or **image**) of f is the vector subspace given by all the images of vectors, that is,

$$R(f) = \{v \in \mathbb{R}^m \mid v = f(u) \text{ for some } u \in \mathbb{R}^n\}.$$

The range of f is the vector space generated by the columns of $M(f)$, and $\dim R(f) = \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is surjective;
2. $\text{rank}(M(f)) = m$;
3. $\dim R(f) = m$.

Range of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **range** (or **image**) of f is the vector subspace given by all the images of vectors, that is,

$$R(f) = \{v \in \mathbb{R}^m \mid v = f(u) \text{ for some } u \in \mathbb{R}^n\}.$$

The range of f is the vector space generated by the columns of $M(f)$, and $\dim R(f) = \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is surjective;
2. $R(f) = \mathbb{R}^m$;
3. $\text{rank}(M(f)) = m$.

Range of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **range** (or **image**) of f is the vector subspace given by all the images of vectors, that is,

$$R(f) = \{v \in \mathbb{R}^m \mid v = f(u) \text{ for some } u \in \mathbb{R}^n\}.$$

The range of f is the vector space generated by the columns of $M(f)$, and $\dim R(f) = \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is surjective;
2. $R(f) = \mathbb{R}^m$;
3. $\text{rank}(M(f)) = m$.

Range of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **range** (or **image**) of f is the vector subspace given by all the images of vectors, that is,

$$R(f) = \{v \in \mathbb{R}^m \mid v = f(u) \text{ for some } u \in \mathbb{R}^n\}.$$

The range of f is the vector space generated by the columns of $M(f)$, and $\dim R(f) = \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is surjective;
2. $R(f) = \mathbb{R}^m$;
3. $\text{rank}(M(f)) = m$.

Range of a linear map

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Definition

The **range** (or **image**) of f is the vector subspace given by all the images of vectors, that is,

$$R(f) = \{v \in \mathbb{R}^m \mid v = f(u) \text{ for some } u \in \mathbb{R}^n\}.$$

The range of f is the vector space generated by the columns of $M(f)$, and $\dim R(f) = \text{rank}(M(f))$.

Proposition

The following are equivalent:

1. f is surjective;
2. $R(f) = \mathbb{R}^m$;
3. $\text{rank}(M(f)) = m$.

Dimensions of Nullspace and Range

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Theorem (The rank theorem)

$$\dim \text{Null}(f) + \dim \text{R}(f) = n$$

Consequences:

- ▶ f is injective $\Leftrightarrow \text{Null}(f) = 0 \Leftrightarrow \dim \text{R}(f) = n$.
- ▶ f is surjective $\Leftrightarrow \dim \text{R}(f) = m \Leftrightarrow \dim \text{Null}(f) = n - m$.
- ▶ f is bijective $\Leftrightarrow n = m$ and $\text{rank}(M(f)) = n$.

Dimensions of Nullspace and Range

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Theorem (The rank theorem)

$$\dim \text{Null}(f) + \dim \text{R}(f) = n$$

Consequences:

- ▶ f is injective $\Leftrightarrow \text{Null}(f) = 0 \Leftrightarrow \dim \text{R}(f) = n$.
- ▶ f is surjective $\Leftrightarrow \dim \text{R}(f) = m \Leftrightarrow \dim \text{Null}(f) = n - m$.
- ▶ f is bijective $\Leftrightarrow n = m$ and $\text{rank}(M(f)) = n$.

Dimensions of Nullspace and Range

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Theorem (The rank theorem)

$$\dim \text{Null}(f) + \dim \text{R}(f) = n$$

Consequences:

- ▶ f is injective $\Leftrightarrow \text{Null}(f) = 0 \Leftrightarrow \dim \text{R}(f) = n$.
- ▶ f is surjective $\Leftrightarrow \dim \text{R}(f) = m \Leftrightarrow \dim \text{Null}(f) = n - m$.
- ▶ f is bijective $\Leftrightarrow n = m$ and $\text{rank}(M(f)) = n$.

Dimensions of Nullspace and Range

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map and let A be its standard matrix.

Theorem (The rank theorem)

$$\dim \text{Null}(f) + \dim \text{R}(f) = n$$

Consequences:

- ▶ f is injective $\Leftrightarrow \text{Null}(f) = 0 \Leftrightarrow \dim \text{R}(f) = n$.
- ▶ f is surjective $\Leftrightarrow \dim \text{R}(f) = m \Leftrightarrow \dim \text{Null}(f) = n - m$.
- ▶ f is bijective $\Leftrightarrow n = m$ and $\text{rank}(M(f)) = n$.

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Composition of linear maps

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^m \rightarrow \mathbb{R}^p$ be linear maps, the **composition** of g with f is the linear map $g \circ f : \mathbb{R}^n \rightarrow \mathbb{R}^p$ defined as:

$$\begin{array}{ccccc} g \circ f : \mathbb{R}^n & \xrightarrow{f} & \mathbb{R}^m & \xrightarrow{g} & \mathbb{R}^p \\ & & v \mapsto f(v) & \mapsto & g(f(v)) \end{array} .$$

If $M(f)$ and $M(g)$ are the standard matrix of f and g respectively, then the standard matrix of $g \circ f$ is

$$M(g \circ f) = M(g) M(f).$$

Composition of linear maps

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^m \rightarrow \mathbb{R}^p$ be linear maps, the **composition** of g with f is the linear map $g \circ f : \mathbb{R}^n \rightarrow \mathbb{R}^p$ defined as:

$$\begin{array}{ccccc} g \circ f : \mathbb{R}^n & \xrightarrow{f} & \mathbb{R}^m & \xrightarrow{g} & \mathbb{R}^p \\ & & v \mapsto f(v) & \mapsto & g(f(v)) \end{array} .$$

If $M(f)$ and $M(g)$ are the standard matrix of f and g respectively, then the standard matrix of $g \circ f$ is

$$M(g \circ f) = M(g) M(f).$$

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.
- The following are equivalent:

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.
- b) The following are equivalent:
1. f is invertible (i.e. bijective)
 2. $\det M(f) \neq 0$
 3. $\text{rank } M(f) = n$
 4. f is an isomorphism
 5. f is surjective

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $M(f) \neq 0$*
 - $M(f)^{-1} = M(g)$*
 - $M(f) \cdot M(g) = M(g) \cdot M(f) = I_n$*
 - $M(f) \cdot M(g) = M(g) \cdot M(f) = I_n$*

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $\det M(f) \neq 0$*
 - $\text{rank}(M(f)) = n$*
 - f is injective*
 - f is surjective*

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $\det M(f) \neq 0$*
 - $\text{rank}(M(f)) = n$*
 - f is injective*
 - f is surjective*

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $\det M(f) \neq 0$*
 - $\text{rank}(M(f)) = n$*
 - f is injective*
 - f is surjective*

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $\det M(f) \neq 0$*
 - $\text{rank}(M(f)) = n$*
 - f is injective*
 - f is surjective*

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $\det M(f) \neq 0$*
 - $\text{rank}(M(f)) = n$*
 - f is injective*
 - f is surjective*

Inverse linear maps

Definition

If $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear maps, we say that g is the **inverse** of f (denoted as $g = f^{-1}$) if $g \circ f = f \circ g = Id$.

Proposition

- a) *If f has standard matrix $M(f)$ and g is the inverse of f , then the standard matrix of g is $M(g) = M(f^{-1}) = (M(f))^{-1}$.*
- b) *The following are equivalent:*
- f is invertible (f is bijective)*
 - $\det M(f) \neq 0$*
 - $\text{rank}(M(f)) = n$*
 - f is injective*
 - f is surjective*

Outline

Definition and examples

Nullspace and Range

Composition

Change of basis

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map, let $B = \{u_1, \dots, u_n\}$ be a basis of \mathbb{R}^n and $C = \{v_1, \dots, v_m\}$ be a basis of \mathbb{R}^m .

Definition

The **matrix of f in bases B, C** has as columns the coordinates of $f(u_1), \dots, f(u_n)$ in the basis C :

$$M_{B,C}(f) = (f(u_1)_C \cdots f(u_n)_C)$$

Properties:

- ▶ $M_{B,C}(f)(w_B) = (f(w))_C$.
- ▶ If B and C are the standard bases, $M_{B,C}(f) = M(f)$.
- ▶ If we compute $\text{Null}(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $\text{Null}(f)$ expressed in the basis B .
- ▶ If we compute $R(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $R(f)$ expressed in the basis C .

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map, let $B = \{u_1, \dots, u_n\}$ be a basis of \mathbb{R}^n and $C = \{v_1, \dots, v_m\}$ be a basis of \mathbb{R}^m .

Definition

The **matrix of f in bases B, C** has as columns the coordinates of $f(u_1), \dots, f(u_n)$ in the basis C :

$$M_{B,C}(f) = (f(u_1)_C \cdots f(u_n)_C)$$

Properties:

- ▶ $M_{B,C}(f)(w_B) = (f(w))_C$.
- ▶ If B and C are the standard bases, $M_{B,C}(f) = M(f)$.
- ▶ If we compute $\text{Null}(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $\text{Null}(f)$ expressed in the basis B .
- ▶ If we compute $R(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $R(f)$ expressed in the basis C .

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map, let $B = \{u_1, \dots, u_n\}$ be a basis of \mathbb{R}^n and $C = \{v_1, \dots, v_m\}$ be a basis of \mathbb{R}^m .

Definition

The **matrix of f in bases B, C** has as columns the coordinates of $f(u_1), \dots, f(u_n)$ in the basis C :

$$M_{B,C}(f) = (f(u_1)_C \cdots f(u_n)_C)$$

Properties:

- ▶ $M_{B,C}(f)(w_B) = (f(w))_C$.
- ▶ If B and C are the standard bases, $M_{B,C}(f) = M(f)$.
- ▶ If we compute $\text{Null}(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $\text{Null}(f)$ expressed in the basis B .
- ▶ If we compute $R(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $R(f)$ expressed in the basis C .

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map, let $B = \{u_1, \dots, u_n\}$ be a basis of \mathbb{R}^n and $C = \{v_1, \dots, v_m\}$ be a basis of \mathbb{R}^m .

Definition

The **matrix of f in bases B, C** has as columns the coordinates of $f(u_1), \dots, f(u_n)$ in the basis C :

$$M_{B,C}(f) = (f(u_1)_C \cdots f(u_n)_C)$$

Properties:

- ▶ $M_{B,C}(f)(w_B) = (f(w))_C$.
- ▶ If B and C are the standard bases, $M_{B,C}(f) = M(f)$.
- ▶ If we compute $\text{Null}(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $\text{Null}(f)$ expressed in the basis B .
- ▶ If we compute $R(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $R(f)$ expressed in the basis C .

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map, let $B = \{u_1, \dots, u_n\}$ be a basis of \mathbb{R}^n and $C = \{v_1, \dots, v_m\}$ be a basis of \mathbb{R}^m .

Definition

The **matrix of f in bases B, C** has as columns the coordinates of $f(u_1), \dots, f(u_n)$ in the basis C :

$$M_{B,C}(f) = (f(u_1)_C \cdots f(u_n)_C)$$

Properties:

- ▶ $M_{B,C}(f)(w_B) = (f(w))_C$.
- ▶ If B and C are the standard bases, $M_{B,C}(f) = M(f)$.
- ▶ If we compute $\text{Null}(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $\text{Null}(f)$ expressed in the basis B .
- ▶ If we compute $R(f)$ using $M_{B,C}(f)$ instead of $M(f)$, we obtain the vectors of $R(f)$ expressed in the basis C .

Change of basis

If $A_{C \rightarrow B}$ is the change-of-basis matrix from C to B (the standard basis of \mathbb{R}^n), and $A_{C' \rightarrow B'}$ is the change-of-basis matrix from C' to B' (the standard basis of \mathbb{R}^m), then:

$$M_{B, B'}(f) = A_{C' \rightarrow B'} M_{C, C'}(f) A_{C \rightarrow B}^{-1},$$
$$M_{C, C'}(f) = A_{C' \rightarrow B'}^{-1} M_{B, B'}(f) A_{C \rightarrow B}.$$