

# Boundary conditions

In a domain  $\Omega$  one has to add boundary conditions to the heat (or diffusion) equation:

- 1.  $u(\mathbf{x}, t) = \phi$  for  $\mathbf{x} \in \partial\Omega$ . Temperature given at the boundary. Also density given at the boundary. (Dirichlet)
- 2.  $ku_{\mathbf{n}}(\mathbf{x}, t) = \phi$  for  $\mathbf{x} \in \partial\Omega$ . Flux given at the boundary. The most typical is  $\phi \equiv 0$ , isolated boundaries. (Neumann)
- 3.  $ku_{\mathbf{n}}(\mathbf{x}, t) + hu(\mathbf{x}, t) = \phi$  for  $\mathbf{x} \in \partial\Omega$ . These are called *convection* boundary conditions in the thermal engineering literature:  $-k\nabla u \cdot \mathbf{n} = h(u - u_{\infty})$  if the temperature of the fluid around the body is  $u_{\infty}$  far away. (third class, Robin, convection, Newton)
- 4. Perfect thermal contact:  $-k_1\nabla u_1 \cdot \mathbf{n} = -k_2\nabla u_2 \cdot \mathbf{n}$ . ( $\mathbf{n}$  is the exterior unit normal to  $\Omega_1$ ).

- 5. Dynamic boundary conditions:  $u_t + \alpha u_n = \phi$  at the boundary.

Example: bar ( $-1 < x < 1$ ) with ends immersed into two fluid containers, at homogeneous temperatures  $a(t)$  and  $b(t)$ .

$$V_f C_f \rho_f \frac{d}{dt} a(t) = \int_A -k u_n dS = A k u_x(-1, t)$$

$$V_f C_f \rho_f \frac{d}{dt} b(t) = -A k u_x(1, t)$$

$a'(t) = \alpha u_x$ ,  $b'(t) = -\alpha u_x$ ,  $u(-1, t) = a(t)$  and  $u(1, t) = b(t)$ .  
So,  $u_t(-1, t) + \alpha(-u_x(-1, t)) = 0$  and  $u_t(1, t) + \alpha u_x(1, t) = 0$ .

Example: (to understand conductivity, or diffusivity) Calculate the steady-state temperature profiles inside a wall  $-1 < x < 1$  made of two parts in perfect thermal contact: one is  $-1 < x < 0$  with conductivity  $k$  and the other is  $0 < x < 1$  of conductivity 1. The boundary temperatures are  $u = 0$  for  $x = -1$  and  $u = 1$  for  $x = 1$ .

$$\begin{cases} u_{xx} = 0, \text{ for } -1 < x < 0 \text{ and } 0 < x < 1, \\ u(-1) = 0, \\ u(0^-) = u(0^+), \quad ku_x(0^-) = u_x(0^+) \\ u(1) = 1. \end{cases}$$

The solution is  $u = (x + 1)/(1 + k)$  for  $-1 < x < 0$  and  $u = (kx + 1)/(1 + k)$  for  $0 < x < 1$ .

**Problem 3.1:** (lumped approximation) Calculate the steady-state temperature profiles inside a wall  $-1 < x < 1$  made of three parts in perfect thermal contact: one is  $-1 < x < -\varepsilon$  with conductivity 1, the second is  $-\varepsilon < x < \varepsilon$  with conductivity  $k$  (small) and the third is  $\varepsilon < x < 1$  with conductivity 1. The boundary temperatures are  $u = a$  for  $x = -1$  and  $u = b$  for  $x = 1$ . Observe that for  $k$  small,  $u \sim a$  in the first part and  $u \sim b$  in the third part. How small (with  $\varepsilon$ ) should  $k$  be to keep this property as  $\varepsilon \rightarrow 0$ ?

## Dissipation and limit behavior (bounded domain)

Imagine  $u_\infty = 0$  and the three cases of boundary values for  $u_t = D\nabla^2 u$ : (1)  $u = 0$ ; (2)  $u_n = -(h/k)u$ , with  $h > 0$ ; and (3)  $u_n = 0$ . One has

$$\frac{d}{dt} \int_{\Omega} \frac{1}{2} u^2 = -D \int_{\Omega} (\nabla u)^2 + D \int_{\partial\Omega} u u_n.$$

In cases (1) and (2) this is strictly negative, unless  $u \equiv 0$ . In case (3) this is strictly negative, unless  $u \equiv \text{constant}$ . Also,

$$\frac{d}{dt} \int_{\Omega} \frac{1}{2} (\nabla u)^2 = -D \int_{\Omega} u_t^2 + D \int_{\partial\Omega} u_t u_n.$$

In cases (1) and (3) this is strictly negative, except at equilibria. In case (2) we have  $\frac{d}{dt} (\int_{\Omega} \frac{1}{2} (\nabla u)^2 + (Dh/k) \int_{\partial\Omega} \frac{1}{2} u^2)$  is strictly negative, except at equilibria.

**Problem 3.2:** By showing that  $\int \frac{1}{2} u^2$  tends exponentially to zero, show that all solutions of  $u_t = D \nabla^2 u$  with  $u = 0$  at  $\partial \Omega$  tend to zero exponentially, provided that  $\Omega$  is *bounded in one direction*, that is  $\Omega \subset \{a < x_i < a + L\}$ . *Hint:* show first Poincaré's inequality. If  $\Omega$  is bounded in some direction and  $u(\mathbf{x})$  is a smooth function in  $\Omega$  that vanishes at  $\partial \Omega$ , then there exists a constant  $C > 0$ , independent of  $u$  such that  $\int_{\Omega} u^2 \leq C \int_{\Omega} (\nabla u)^2$ .

Can one show, with similar methods, that all the solutions of  $u_t = D \nabla^2 u$  with  $u_n = 0$  at  $\partial \Omega$  tend exponentially to a steady solution? Given the initial condition  $u(\mathbf{x}, 0)$  can one predict which is the value of the constant solution at which  $u(\mathbf{x}, t)$  tends as  $t \rightarrow \infty$ ?

## Dissipation and limit behavior (infinite domain)

Dimension one,  $k = 1$ . Non-negative solutions with finite mass:  
 $0 \leq u(x, 0)$ ,  $\|u(\cdot, 0)\|_1 < \infty$ .

$$0 \leq u(x, t) \leq \frac{1}{\sqrt{4\pi t}} \|u(\cdot, 0)\|_1.$$

Also, we have the particular solutions

$G(x, t) = (4\pi t)^{-1/2} e^{-x^2/(4t)}$ . So,  $t^{-1/2}$  is the optimal power.

**Problem 3.3:** Suppose  $0 \leq u(x, 0)$ ,  $\|u(\cdot, 0)\|_1 < \infty$ , and  $u(x, 0)$  nonzero. Prove that there is a value  $x_0$  and a constant  $C > 0$  such that  $u(x_0, t) \geq C/\sqrt{t}$  for  $t$  sufficiently large.

For large  $t$  every positive solution approaches a Gaussian:

Suppose  $0 \leq u(x, 0) \leq M_1(1 + x^2)^{-\alpha}$  for some  $\alpha > 1$ , and that  $\|u(\cdot, 0)\|_1 = M_2$ . Then it can be proved that  $\|u(\cdot, t) - M_2 G(\cdot, t)\|_\infty \sim 1/t$ .

## Entropy

If an event happens with probability  $p$ , its (Shannon) amount of information is  $-\log p$ . If there are  $n$  possible events, with probabilities  $p_i$ , the (Shannon) *entropy*  $H$  of the system is the expected value of the amount of information:  $\sum -p_i \log p_i (> 0)$ .

If we have a pdf  $u(x)$  for  $-\infty < x < \infty$  and a partition  $\{ih \leq x < (i+1)h, k \in \mathbb{Z}\}$  the entropy would be

$$\sum_i - \left( \int_{ih}^{(i+1)h} u \, dx \right) \log \left( \int_{ih}^{(i+1)h} u \, dx \right) \simeq$$
$$\sum_i -u(ih)h \log(u(ih)h) \simeq -\log h - \int_{-\infty}^{\infty} u \log u \, dx$$

and we define its (*renormalized*) entropy as

$h[u] = - \int_{-\infty}^{\infty} u \log u \, dx$ . Observe that needs not to be positive.



If  $u$  satisfies  $u_t = u_{xx}$  then

$$\begin{aligned} \frac{d}{dt} h[u] &= - \int u_{xx} \log u - \underbrace{\int u_{xx}}_{=0} = \int \left( -(u_x \log u)_x + |u_x|^2/u \right) = \\ & \int |u_x|^2/u > 0, \end{aligned}$$

so the entropy always increases. The same is true in  $n$  dimensions or in a bounded domain with Neumann boundary conditions. Also, for the gaussian

$$- \int G \log G = - \int \frac{1}{\sqrt{4\pi t}} e^{-\frac{x^2}{4t}} \left( \log \frac{1}{\sqrt{4\pi t}} - \frac{x^2}{4t} \right)$$

**Problem 3.4:** Show that the first term tends to infinity as  $\log t$  and the second does not depend on  $t$ .

## Separation of variables in an interval

$$u_t = u_{xx} \text{ in } 0 < x < a$$

$$u_x(0) = u_x(a) = 0$$

$$u(x, t) = \sum_{n=0}^{\infty} \alpha_n e^{-n^2 \frac{\pi^2}{a^2} t} \cos n \frac{\pi}{a} x$$

$$\alpha_0 = \frac{1}{a} \int_0^a u(x, 0) dx, \quad \alpha_n = \frac{2}{a} \int_0^a u(x, 0) \cos \frac{n\pi}{a} x dx.$$

## Separation of variables in a rectangle

$u_t = \nabla^2 u$  in  $0 < x < a$ ,  $0 < y < b$  with Neumann boundary conditions.

$$u(x, y, t) = \sum_{n,m=0}^{\infty} \alpha_{nm} e^{-(n^2 \frac{\pi^2}{a^2} + m^2 \frac{\pi^2}{b^2})t} \cos(n \frac{\pi}{a} x) \cos(m \frac{\pi}{b} y) =$$

$$\sum_{n=0}^{\infty} \alpha_{n0} e^{-n^2 \frac{\pi^2}{a^2} t} \cos(n \frac{\pi}{a} x) +$$

$$\sum_{n,m=1}^{\infty} \alpha_{nm} \underbrace{e^{-(n^2 \frac{\pi^2}{a^2} + m^2 \frac{\pi^2}{b^2})t}}_{\leq e^{-\pi^2 t/b^2}} \cos(n \frac{\pi}{a} x) \cos(m \frac{\pi}{b} y).$$

So, if  $0 < b \ll 1$   $u$  becomes shortly independent of  $y$  and satisfies simply  $u_t = u_{xx}$  in  $0 < x < a$  with Neumann boundary conditions.

## Thin (slender) domains

$\Omega_\varepsilon = \{(x, y) | 0 < x < a, 0 < y < \varepsilon g(x)\}$ ,  $u_t = D\nabla^2 u$  in  $\Omega_\varepsilon$ ,

$\partial u / \partial \mathbf{n} = 0$  on  $\partial\Omega_\varepsilon$ . Suppose

$u(x, y, t) = u^0(x, t) + \varepsilon u^1(x, y, t) + O(\varepsilon^2)$ , and the same for the  $x$ -derivatives.

$$\frac{d}{dt} \int_{x_1}^{x_2} \int_0^{\varepsilon g(x)} u(x, y, t) dy dx = \int_0^{\varepsilon g(x_2)} Du_x dy - \int_0^{\varepsilon g(x_1)} Du_x dy$$

$$\frac{d}{dt} \int_{x_1}^{x_2} \varepsilon g(x) u^0(x, t) dx = \varepsilon g(x_2) Du_x^0(x_2, t) - \varepsilon g(x_1) Du_x^0(x_1, t)$$

$$\int_{x_1}^{x_2} g(x) u_t^0(x, t) dx = \int_{x_1}^{x_2} (g(x) Du_x^0(x, t))_x dx$$

$$u_t^0 = \frac{D}{g(x)} (g(x) u_x^0)_x, \quad u_t^0 = Du_{xx}^0 + D \frac{g'(x)}{g(x)} u_x^0.$$