The inner equation for one and a half degrees of freedom rapidly forced Hamiltonian systems

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Abstract
We consider families of one and a half degrees of freedom rapidly forced Hamiltonian systems which are perturbations of one degree of freedom Hamiltonians with a homoclinic connection. We derive the inner equation for this class of Hamiltonian system which is expressed as the Hamiltonian–Jacobi equation of a one a half degrees of freedom Hamiltonian. The inner equation depends on a parameter not necessarily small.

We prove the existence of special solutions of the inner equation with a given behaviour at infinity. We also compute the asymptotic expression for the difference between these solutions. In some perturbative cases, this asymptotic expression is strongly related with the Melnikov function associated with our initial Hamiltonian.

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1. Introduction

The phenomenon known as splitting of separatrices has been widely studied by several authors. This phenomenon arises, for instance, when we consider a differential equation in $\mathbb{R}^2$ with a fixed point having coincident branches of stable and unstable manifolds and we perturb it by a periodic or quasi-periodic function on time.

The simplest framework—the regular case—is when the perturbation is regular with respect to the perturbation parameter, ε. For such a situation, Melnikov [18] (developing some ideas by Poincaré) gave a tool, which is called Poincaré–Melnikov function, to provide asymptotic expressions of the distance (and other related quantities) between the perturbed invariant manifolds when $\varepsilon \to 0$.

If the perturbation is not regular for ε, for instance, because it depends periodically on t/ε, then the Poincaré–Melnikov function does not give, *a priori*, the right estimate of the measure of the splitting of separatrices, which in the Hamiltonian case is always exponentially small in ε (see [10] for the periodic case). These singular cases are also known as rapidly forced systems. The phenomenon of exponentially small splitting of separatrices had already been discovered by Poincaré [21] in a near integrable case.

In 1964, Arnold [2], when studying the diffusion on the action variables of the near integrable systems $h_0(I) + \varepsilon h_1(\varphi, I, \varepsilon)$, realized that the splitting of separatrices associated with partially hyperbolic tori was exponentially small in ε.

In the setting of planar systems with high frequency periodic perturbations, upper bounds of the splitting of separatrices have been given in [10, 11, 16]. If we restrict ourselves to one and a half degrees of freedom rapidly forced Hamiltonian systems, under suitable conditions, asymptotic expressions validating the prediction given by the Poincaré–Melnikov function can be found in [3, 7, 8, 13] (see also references therein). Two of the more important techniques used in these studies are the suitable flow box coordinates around the stable invariant manifold and the extension lemma. In [25] a more general perturbation of the pendulum is considered. The author uses a different method, based on a continuous averaging procedure, for proving an asymptotic formula of the splitting of separatrices which differs from the one predicted by the Poincaré–Melnikov function.

In the examples above the given asymptotic expressions are of the form $\varepsilon^r e^{-a/\varepsilon}$, but it is possible to find systems where the true asymptotic formula does not have this form (see [24]).

This problem can also be studied for planar maps. Lazutkin wrote the first study on this subject, [17], in which he gave an asymptotic formula for the splitting of separatrices of the standard map. The complete proof of this can be found in [14]. In this context in [12] exponentially small upper bounds for the splitting of separatrices are proved for analytic families of diffeomorphisms close to the identity. In [6] is proved an asymptotic expression for the splitting of separatrices for some perturbations of the McMillan map, which is also exponentially small and, in fact, coincides with the prediction given by the Poincaré–Melnikov function.

In [23], the author introduces a new method to study the splitting of separatrices in Hamiltonian systems which is illustrated in the generalized Arnol'd model with $d+1$ degrees of freedom ($d \geqslant 2$). In the model considered in [23] a fixed torus with stable and unstable invariant manifolds is left invariant after perturbation. The stable and unstable invariant manifolds are given as solutions of the Hamilton–Jacobi equation. The main tool for studying the splitting of separatrices is a characteristic vector field, which is defined on a part of the configuration space, has constant coefficients in good variables and acts on the difference of the stable and unstable manifold by zero. Actually upper bounds of the splitting of separatrices are given in a general setting and also lower bounds for special cases are proved.

Recently, resurgence theory (see [5, 9]) has also been used in the problem of the exponentially small splitting of separatrices. In [22] the author studies the rapidly forced pendulum by using parametric resurgence. Resurgence theory can also be used in the study of the exponentially small splitting of separatrices for a map, see [15], where the authors deal with the Hénon map.

The study we present in this paper is close to another strategy based on matching complex techniques (see [4]). This method will allow us to study the splitting of separatrices in the singular case, for instance in the case of one and a half degrees of freedom rapidly forced Hamiltonian, $H_{\mu,\varepsilon}$ of the form

$$H_{\mu,\varepsilon}(x, y, t/\varepsilon) = h_0(x, y) + \mu h_1(x, y, t/\varepsilon, \mu, \varepsilon), \qquad (1.1)$$

where h_1 is 2π-periodic with respect to t/ε. Suppose that $H_{0,\varepsilon}$ has a homoclinic connection and that it can be parametrized by a complex parameter $u \in \{z \in \mathbb{C} : |\mathrm{Im}\, z| < a\}$ for some $a > 0$. Assume that this parametrization has only two singularities on $\{z \in \mathbb{C} : |\mathrm{Im}\, z| = a\}$ located at points $u = \pm ia$. These hypotheses are satisfied, for instance, by the pendulum. Roughly speaking, the method is as follows.

(1) To simplify the exposition, we consider the Hamilton–Jacobi equation associated with equation (1.1). The perturbed invariant manifolds will be described by means of two special solutions of the Hamilton–Jacobi equation, $\phi^\pm$, satisfying an asymptotic condition.

(2) We prove the existence of parametrizations, $\phi^\pm$, of the perturbed invariant manifolds in the so called *outer domain*, O. In this domain, the invariant manifolds $\phi^\pm$ are well approximated by the homoclinic connection.

(3) We look for good approximations of the perturbed invariant manifolds near the singularities of the homoclinic connection. For this, we derive the *inner equation*, which is independent of ε. These approximations are merely special solutions, $\phi_{\mathrm{in}}^\pm$, of the so called *inner equation* and they are useful only in a small neighbourhood of the singularities: the *inner domain*, I. In the *inner domain* the homoclinic connection is not a good approximation of the invariant manifolds. It is necessary that $I \cap O \neq \emptyset$ and $O \cup I = \{z \in \mathbb{C} : |\mathrm{Im}\, z| < a\}$. We also compute the asymptotic expression of the difference between ϕ_{in}^+ and ϕ_{in}^-.

(4) By using matching complex techniques, the functions $\phi_{\mathrm{in}}^\pm$ in the *inner domain* must be connected with the invariant manifolds $\phi^\pm$ in the *outer domain*.

(5) Finally, it is necessary to prove that the dominant term of the splitting of separatrices, $\phi^- - \phi^+$, is given by the one obtained in the *inner domain*, $\phi_{\mathrm{in}}^- - \phi_{\mathrm{in}}^+$.

By using this strategy it seems possible to deal with larger perturbations. See [19] for a good summary.

In this work we perform step (3) mentioned above by considering an *inner equation* which comes from a quite general one and a half degrees of freedom rapidly forced Hamiltonian. In [20], an *inner equation* derived from an example of a rapidly forced pendulum is studied by using equational resurgence. Note that we will not use resurgence theory; our approach is close to the one given in [23].

Using the results of this paper, we plan, in a forthcoming work, to give an asymptotic expression for the splitting of separatrices for one and a half degrees of freedom rapidly forced Hamiltonian systems having more general perturbations than the ones considered up to now.

The paper is organized as follows. In section 2 we explain the problem and the motivation to study it. In section 3 we introduce notation and state the main results. Sections 4–6 are devoted to the proof of the results of section 3. Finally, even though the proofs we will present in this work deal with the analytic case, we have included an appendix where we state and prove results similar to the ones given in section 3 for Hamiltonians which are only differentiable with respect to time. We distinguish between the analytic and the non-analytic dependence on time in order to clarify the exposition.

2. Context and motivation

2.1. The problem

Consider the Hamiltonian $\mathcal{H} = \mathcal{H}_0 + \mu\mathcal{H}_1$, where μ is a not necessarily small parameter,

$$\mathcal{H}_0(z, w) = \frac{1}{2}w^2 z^{2r} - \frac{1}{2z^{2r}}, \qquad \mathcal{H}_1(z, w, \tau, \mu) = \frac{1}{z^\ell} \sum_{j=0}^{N} A_j(\tau, \mu) w^j z^{2rj}, \tag{2.1}$$

$r \geqslant 1$, $\ell \in \mathbb{R}$, $N \in \mathbb{N}$. Moreover $\{A_j\}_{j \in \{0,...,N\}}$ are arbitrary analytic functions in (τ, μ), 2π-periodic and having zero mean with respect to τ.

Our goal is to study the existence and properties of two special solutions $\phi_{\text{in}}^{\pm}$ of the Hamilton–Jacobi equation associated with the Hamiltonian $\mathcal{H}$:

$$\partial_\tau \phi + \mathcal{H}(z, \partial_z \phi, \tau, \mu) = 0, \tag{2.2}$$

satisfying that $\phi_{\text{in}}^{\pm}$ are analytic in some complex domain $E^{\pm}$, $\phi_{\text{in}}^{\pm}$ are 2π-periodic with respect to τ and have the asymptotic property

$$\lim_{\text{Re}\, z \to \pm\infty} \partial_z \phi_{\text{in}}^{\pm}(z, \tau, \mu) = 0. \tag{2.3}$$

We are also interested in computing the asymptotic expression of the difference $\partial_z(\phi_{\text{in}}^{-} - \phi_{\text{in}}^{+})(z, \tau, \mu)$ as $\mu \to 0$ and $\text{Im}\, z \to -\infty$.

To shorten the notation, along this work we will denote $\phi_{\text{in}}^{\pm}$ simply by $\phi^{\pm}$.

2.2. The model: an inner equation

The Hamiltonian defined by $\mathcal{H}$ arises naturally from Hamiltonians of the form

$$H_{\mu,\varepsilon}(q, p, t/\varepsilon) = \tfrac{1}{2} p^2 + V(q) + \mu\varepsilon^m h_1(q, p, t/\varepsilon, \mu, \varepsilon) \tag{2.4}$$

such that the unperturbed system (given by $H_{0,\varepsilon}$) has a homoclinic connection. Indeed, assume that V is an analytic function, h_1 is analytic with respect to (p, q, μ) and $2\pi\varepsilon$-periodic with respect to t. Moreover assume that the Hamiltonian system given by $H_{\mu,\varepsilon}$, when $\mu = 0$ has the origin as a saddle fixed point, that one branch of the stable invariant manifold coincides with one branch of the unstable one, giving rise to a homoclinic connection, which can be parametrized by a complex parameter u. We denote it by $\gamma_0(u) = (q_0(u), p_0(u))$ and we suppose that $\gamma_0(u)$ is analytic in the complex strip $S_a = \{u \in \mathbb{C} : |\text{Im}\, u| < a\}$, that it has singularities at $u = \pm ia$, that it has no other singularities in $\{u \in \mathbb{C} : |\text{Im}\, u| = a\}$ and that in a neighbourhood of $\pm ia$, there exist $r > 1$, $C_{\pm} \in \mathbb{C}$ and functions g, h with $g(0) = h(0) = 0$ in such a way that γ_0 can be written as

$$q_0(u) = -\frac{C_{\pm}}{(r-1)} \frac{1}{(u \mp ia)^{r-1}} (1 + g(u \mp ia)), \quad p_0(u) = \frac{C_{\pm}}{(u \mp ia)^r} (1 + h(u \mp ia)). \tag{2.5}$$

Without loss of generality we can assume that $V(0) = 0$. Hence

$$V(q_0(u)) = -\frac{p_0^2}{2} = -\frac{C_{\pm}^2}{(u \mp ia)^{2r}} (1 + f(u \mp ia)) \tag{2.6}$$

with $f(0) = 0$.

We now consider the symplectic change of variables given by

$$\tau = \frac{t}{\varepsilon}, \qquad q = q_0(u), \qquad p = \frac{v}{p_0(u)},$$

which is well defined, in a neighbourhood of ia intersected with S_a. We notice that the homoclinic orbit can be expressed locally in the new variables as $(u, p_0^2(u))$ and the new Hamiltonian is merely $\bar{H}_{\mu,\varepsilon}(u, v, \tau) = \varepsilon H_{\mu,\varepsilon}(q_0(u), v/p_0(u), \tau)$. With this change of variables we have control over the definition domain of the variable u (which will be a neighbourhood of $\pm ia$ intersected with the complex strip S_a). Moreover, since in these variables the homoclinic connection γ_0 can be written as the graph of a suitable function, we expect that the invariant manifolds of the new Hamiltonian also will be expressed as the graph of adequate functions.

We are looking for a new Hamiltonian $\mathcal{H}$ which will be a good approximation of $H_{\mu,\varepsilon}$ in a neighbourhood of the singularity $u = ia$ (one can proceed in an analogous way to study the singularity $u = -ia$). For this reason, we perform the change of variables given by $z = (u - ia)/\varepsilon$, $w = \varepsilon^{2r} C_+^{-2} v$. This change has constant determinant and therefore the new system is also Hamiltonian with Hamiltonian

$$\overline{\mathcal{H}}_{\mu,\varepsilon}(z, w, \tau) = \varepsilon^{2r-1} C_+^{-2} \overline{H}_{\mu,\varepsilon}(\varepsilon z + ia, w\varepsilon^{-2r} C_+^2, \tau)$$

$$= \varepsilon^{2r} C_+^{-2} \left(\frac{C_+^4 w^2}{\varepsilon^{4r} p_0^2(\varepsilon z + ia)} + V(q_0(\varepsilon z + ia)) \right)$$

$$+ C_+^{-2} \mu \varepsilon^{m-2r} h_1 \left(q_0(\varepsilon z + ia), \frac{C_+^2 w}{\varepsilon^{2r} p_0(\varepsilon z + ia)}, \tau, \mu, \varepsilon \right).$$

We assume another condition over h_1: h_1 is a polynomial in the (q, p) variables, that is, $h_1(q, p, \tau, \mu, \varepsilon) = \sum_{0 \leqslant i,j \leqslant M} a_{i,j}(\tau, \mu, \varepsilon) q^i p^j$. Therefore we can define

$$\ell = \max\{(r-1)i + rj : \forall \mu_0, \varepsilon_0 > 0, \exists (\tau, \mu, \varepsilon) \in [0, 2\pi] \times [-\mu_0, \mu_0] \times (0, \varepsilon_0)$$
$$\text{s.t. } a_{i,j}(\tau, \mu, \varepsilon) \neq 0\}.$$

In other words, ℓ is the greatest order of the singularities $\pm ia$ among all the monomials of h_1. This quantity ℓ was also defined in [8].

Using expressions (2.5) and (2.6) of $q_0(u)$, $p_0(u)$ and $V(q_0(u))$ and taking into account the definition of ℓ, we conclude that

$$\overline{\mathcal{H}}_{\mu,\varepsilon}(z, w, \tau) = \mathcal{H}_0(z, w) + \mu \varepsilon^{m-\ell+2r} \mathcal{H}_1(z, w, \tau, \mu)(1 + f_\varepsilon) + g_\varepsilon \qquad (2.7)$$

where $\mathcal{H}_0$ and $\mathcal{H}_1$ are of the form (2.1) and $f_0 = g_0 = 0$.

Remark 2.1. It is not difficult to see that we also obtain a system of the form (2.7) if both V and h_1 are trigonometric polynomials with respect to q, and h_1 is a polynomial with respect to p. In this case we allow $r \geqslant 1$.

Taking $m = \ell - 2r$, and considering system (2.7) for $\varepsilon = 0$, we get a Hamiltonian system with Hamiltonian $\mathcal{H}$. Hence, the study of the existence and properties of solutions $\phi^\pm$ of the Hamilton–Jacobi equation (2.2) is strongly related to the study of the invariant manifolds of Hamiltonian systems of the form (2.4). Obviously, if $m > \ell - 2r$ we can rename $\mu \varepsilon^{m-\ell+2r}$ by μ and proceeding as in the case $m = \ell - 2r$. The case $m < \ell - 2r$ remains unknown.

Remark 2.2. Consider system (2.7) for $\mu = \varepsilon = 0$. In this case, the approximation of the piece of the stable (or unstable) invariant manifold we are dealing with can be represented in the new variables (z, w) as $(z, 1/z^{2r})$.

Remark 2.3. The previous procedure is a generalization of the idea given in [20] for obtaining an inner equation for a perturbed pendulum. In our case the homoclinic connection is not a Lagrangian manifold, thus we cannot deal with the Hamilton–Jacobi equation from the beginning as in [20].

3. Main results

Before presenting the precise statement of the results, let us fix some notation.

For any $b > 0$ and $\mu_0 > 0$ we introduce the complex strip $S_b = \{\tau \in \mathbb{C} : |\text{Im}\,\tau| < b\}$ and the open ball $B(\mu_0) = \{\mu \in \mathbb{C} : |\mu| < \mu_0\}$.

Let $\gamma, \rho > 0$. We define the complex domains

$$D_{\gamma,\rho}^+ = \{z \in \mathbb{C} : |\mathrm{Im}\, z| > -\gamma\, \mathrm{Re}\, z + \rho\}, \qquad D_{\gamma,\rho}^- = -D_{\gamma,\rho}^+,$$

$$E_{\gamma,\rho} = D_{\gamma,\rho}^+ \cap D_{\gamma,\rho}^- \cap \{z \in \mathbb{C} : \mathrm{Im}\, z < 0\}. \tag{3.1}$$

To shorten the notation we write $\mathcal{D}_{\gamma,\rho,b}^\pm = D_{\gamma,\rho}^\pm \times S_b \times B(\mu_0)$ and $\mathcal{E}_{\gamma,\rho,b} = E_{\gamma,\rho} \times S_b \times B(\mu_0)$.

The first result is related to the existence of analytic solutions, $\phi^\pm$, of the Hamilton–Jacobi equation (2.2), satisfying that $\lim_{\mathrm{Re}\, z \to \pm\infty} \partial_z \phi^\pm = 0$ and that are 2π-periodic with respect to τ.

Theorem 3.1. *Consider the Hamiltonian $\mathcal{H} = \mathcal{H}_0 + \mu\mathcal{H}_1$, where*

$$\mathcal{H}_0(z,w) = \frac{1}{2}w^2 z^{2r} - \frac{1}{2z^{2r}} \quad \text{and} \quad \mathcal{H}_1(z,w,\tau,\mu) = \frac{1}{z^\ell}\sum_{j=0}^N A_j(\tau,\mu)w^j z^{2rj}, \tag{3.2}$$

with $r \geqslant 1$, $\ell \in \mathbb{R}$, $N \in \mathbb{N}$.

Assume that $\{A_j\}_{j\in\{0,\ldots,N\}}$ are analytic functions on $S_{b_0} \times B(\mu_0)$ for some $b_0 > 0$ and $\mu_0 > 0$ and that they are 2π-periodic, with zero mean, with respect to τ.

Then, if $\ell \geqslant 2r$, for any $\gamma > 0$ and $0 < b < b_0$ there exists $\rho_0 = \rho_0(\gamma,b,\ell,r,\mu_0) > 0$, such that the Hamilton–Jacobi equation associated with $\mathcal{H}$

$$\partial_\tau \phi + \mathcal{H}(z, \partial_z\phi, \tau, \mu) = 0 \tag{3.3}$$

has solutions $\phi^\pm : \mathcal{D}_{\gamma,\rho_0,b}^\pm \to \mathbb{C}$ of the form

$$\phi^\pm(z,\tau,\mu) = -\frac{1}{(2r-1)z^{2r-1}} + \mu\phi_1^\pm(z,\tau,\mu) + \xi^\pm, \qquad \xi^\pm \in \mathbb{C},$$

where $\phi_1^\pm$ are analytic functions in all their variables and 2π-periodic with respect to τ. Moreover the derivatives $\partial_z\phi_1^\pm$ are uniquely determined by the condition

$$\sup_{(z,\tau,\mu)\in\mathcal{D}_{\gamma,\rho_0,b}^\pm} |z^{\ell+1}\partial_z\phi_1^\pm(z,\tau,\mu)| < +\infty. \tag{3.4}$$

Remark 3.2. We define $\varepsilon_\tau = (b_0 - |\mathrm{Im}\,\tau|)/2$ and the complex set

$$D_\gamma(\tau,\mu) = \{z \in \mathbb{C} : |\mathrm{Im}\, z| > -\gamma\,\mathrm{Re}\, z + \rho_0(\gamma, |\mathrm{Im}\,\tau| + \varepsilon_\tau, \ell, r, |\mu|)\}.$$

It can be proved that the solutions of the Hamilton–Jacobi equation given in theorem 3.1, $\phi^\pm$, are analytic functions in $(z,\tau,\mu) \in D_\gamma(\tau,\mu) \times S_{b_0} \times B(\mu_0)$, respectively, and therefore we do not lose the analyticity domain with respect to (τ,μ) provided $z \in D_\gamma(\tau,\mu)$.

The proof of theorem 3.1 is given in section 4.

Let $\phi^\pm$ be two solutions of the Hamilton–Jacobi equation (3.3) satisfying the conclusions of theorem 3.1. Our goal now will be to give an asymptotic expression for the difference between $\partial_z\phi^-$ and $\partial_z\phi^+$ as $\mathrm{Im}\, z \to -\infty$.

To state the next result properly we need to introduce some notation. We write

$$Q_j(\tau,\mu) = \sum_{k=j}^N \binom{k}{j} A_k(\tau,\mu), \qquad j = 0,\ldots,N$$

and we define F_0 such that $\partial_\tau F_0 = Q_0$ and $\langle F_0 \rangle = 0$ where $\langle \cdot \rangle$ denotes, as usual, the mean with respect to τ.

Theorem 3.3. *Under the conditions of theorem 3.1, there exist $\rho_1 = \rho_1(\gamma,b,\ell,r,\mu_0) \geqslant \rho_0$, an analytic function $C(\mu)$ defined on $B(\mu_0)$ and an analytic function $g : \mathcal{E}_{\gamma,\rho_1,b} \to \mathbb{C}$ such that, for any two solutions $\phi^\pm$ of equation (3.3) given by theorem 3.1,*

$$\partial_z(\phi^- - \phi^+)(z,\tau,\mu) \sim -\mathrm{i}\mu C(\mu)\mathrm{e}^{-\mathrm{i}(z-\tau+\mu g(z,\tau,\mu))} \qquad \text{as } \mathrm{Im}\, z \to -\infty. \tag{3.5}$$

We also have that

$$- \mathrm{i} C(0) \mathrm{e}^{-\mathrm{i}(z-\tau)} \sim \ell \int_{-\infty}^{+\infty} \frac{Q_0(\tau+t,0)}{(z+t)^{\ell+1}} \, \mathrm{d}t \qquad \text{as } \operatorname{Im} z \to -\infty, \qquad (3.6)$$

where $\{A_j\}_{j \in \{0, \cdots, N\}}$ are defined by (3.2).

Moreover the function g satisfies that

$$\sup_{(z,\tau,\mu) \in \mathcal{E}_{\gamma,\rho_1,b}} |z^{\ell-2r} g(z,\tau,\mu)| < \infty \qquad \text{if } \ell > 2r,$$

$$\sup_{(z,\tau,\mu) \in \mathcal{E}_{\gamma,\rho_1,b}} |(\log |z|)^{-1} g(z,\tau,\mu)| < \infty \qquad \text{if } \ell = 2r \text{ and either } Q_1 \neq 0 \text{ or } \langle F_0 \cdot Q_2 \rangle \neq 0,$$

$$\sup_{(z,\tau,\mu) \in \mathcal{E}_{\gamma,\rho_1,b}} |z g(z,\tau,\mu)| < \infty \qquad \text{if } \ell = 2r, \ Q_1 = 0 \text{ and } \langle F_0 \cdot Q_2 \rangle = 0.$$

Remark 3.4. We emphasize that the function g given in theorem 3.3 does not depend on the choice of $\phi^{\pm}$. In fact we will see that g only depends on $\partial_z \phi^{\pm}$ which are determined uniquely by condition (3.4).

The proof of theorem 3.3 will be left to section 5. The main idea of proving this theorem is to exploit the fact that the difference $\partial_z(\phi^- - \phi^+)$ satisfies a linear equation with suitable properties. This idea was already introduced in [23] although the way we deal with this linear equation is different.

Let us denote $a^k(\mu)$ the k-Fourier coefficient of $Q_0(\tau, \mu)$. The following corollary gives an explicit asymptotic formula of $\partial_z(\phi^- - \phi^+)$ as $\mu \to 0$ and $\operatorname{Im} z \to -\infty$.

Corollary 3.5. *Under the same assumptions of theorem 3.1 and the condition $a^1(0) \neq 0$, the following asymptotic formulas hold.*

(i) If either $\ell > 2r$ or $\ell = 2r$, $Q_1 = 0$ and $\langle F_0 \cdot Q_2 \rangle = 0$,

$$\partial_z(\phi^- - \phi^+)(z,\tau,\mu) \sim \mu \mathrm{i}^{\ell+1} \frac{2\pi\ell}{\Gamma(\ell+1)} a^1(0) \mathrm{e}^{-\mathrm{i}(z-\tau)}, \qquad \operatorname{Im} z \to -\infty, \mu \to 0.$$

(ii) If $\ell = 2r$ and either $Q_1 \neq 0$ or $\langle F_0 \cdot Q_2 \rangle \neq 0$,

$$\partial_z(\phi^- - \phi^+)(z,\tau,\mu) \sim \mu \mathrm{i}^{\ell+1} \frac{2\pi\ell}{\Gamma(\ell+1)} a^1(0) \mathrm{e}^{-\mathrm{i}(z-\tau+\mu g(z,\tau,0))}, \qquad \operatorname{Im} z \to -\infty, \mu \to 0.$$

We will check corollary 3.5 in section 6.

If there is no danger of confusion, we will omit the dependence with respect to the parameters μ and μ_0 in the notation. Throughout the paper this dependence will be analytic.

3.1. Remarks

- We stress that theorems 3.1 and 3.3 apply for not necessarily small values of μ.
- Note that our results are only valid if $\ell \geqslant 2r$. The case $\ell < 2r$ must be treated differently.
- Our results agree with those on the difference between ϕ^+ and ϕ^- given in [20] for the particular case

$$\partial_\tau \phi - \frac{1}{8} z^2 (\partial_z \phi)^2 + 2 \frac{1}{z^2}(1 - \mu \sin \tau) = 0.$$

Performing the linear change $\phi = -4\psi$ we obtain equation (3.3) for $r = 1$, $\ell = 2$ and $\mathcal{H}_1 = z^{-2}(\sin \tau)/2$. In this case, $N = 0$ and hence $Q_1 = 0$ and $\langle F_0 \cdot Q_2 \rangle = 0$.

- We notice that the asymptotic expression given in corollary 3.5 is closely related to the Melnikov function M of the Hamiltonian system $H_{\mu,\varepsilon}$, defined in (2.4). In this case we are considering μ to be a small parameter. In fact, assuming the hypotheses of section 2.2 if either $\ell > 2r$ or $\ell = 2r$, $Q_1 = 0$ and $\langle F_0 \cdot Q_2 \rangle = 0$, we have that

$$\mu \varepsilon^\ell M(u, \varepsilon) \sim 2 \operatorname{Re}(C_+^2 \partial_z (\phi^+ - \phi^-))((u - ia)/\varepsilon, 0)). \tag{3.7}$$

Indeed, let $J(q, p, \tau) = \{h_0, h_1\}(q, p, \tau)$ and let $J_k(q, p)$ be its k-Fourier coefficient. It is clear that there exist functions $h_k^\pm$ satisfying $h_k^\pm(0) = 0$ such that

$$J_k(q_0(u), p_0(u)) = \frac{J_{k,0}^\pm}{(u \pm ia)^{\ell+1}} (1 + h_k^\pm (u \pm ia)),$$

in a neighbourhood of $u = \mp ia$, respectively. We note that $J_{k,0}^+ = \overline{J_{k,0}^-}$. In [3] and [8] (for $\ell \in \mathbb{N}$) it is proved that, if $J_{1,0}^- \neq 0$, then

$$\varepsilon^\ell M(u, \varepsilon) \sim \frac{4\pi}{\Gamma(\ell+1)} \operatorname{Re}(i^{\ell+1} J_{1,0}^- e^{-iu/\varepsilon}) e^{-a/\varepsilon}.$$

Following the changes of variables given in section 2.2, tedious but easy computations show that

$$\sum_{j=0}^N A_j(\tau, \mu) = \frac{1}{\ell C_+^2} \sum_{k \in \mathbb{Z} \setminus \{0\}} J_{k,0}^- e^{ik\tau}.$$

Thus $J_{1,0}^- = a^1(0) \ell C_+^2$. Finally formula (3.7) follows from the asymptotic expression given in (i) of corollary 3.5.

- In the case $\ell = 2r$ and either $Q_1 \neq 0$ or $\langle F_0 \cdot Q_2 \rangle \neq 0$, the difference $\partial_z(\phi^- - \phi^+)$ has an extra term given by the function g which is not related (a $priori$) to the Melnikov function. We expect that, in the cases where g be of order $\log|z|$, the Melnikov function will not measure the splitting of separatrices even when the parameter μ is small.

  This case is fulfilled, for instance, if we look for the inner equation for the perturbed pendulum

$$H_{\mu,\varepsilon}(q, p, t/\varepsilon) = \tfrac{1}{2} p^2 + (1 - \cos q) + \mu(p^2 \cos(t/\varepsilon) + \cos q \sin(t/\varepsilon)).$$

Indeed, the homoclinic orbits are given by

$$(q_0(u), p_0(u)) = (\pm 2 \arctan(\sinh u), \pm 2 \operatorname{sech} u).$$

Let us consider the $+$ sign. The second component has poles of order 1 at $u = \pm i\pi/2 + 2k\pi$. Hence, following the notation given in section 2, one has that $r = 1$, $a = \pi/2$ and $C_+ = -2i$. Writing $h_1(q, p, \tau, \mu, \varepsilon) = p^2 \cos(t/\varepsilon) + \cos q \sin(t/\varepsilon)$, we obtain

$$\frac{\varepsilon^2}{C_+^2} h_1 \left(q_0(\varepsilon z + ia), \frac{C_+^2 w}{\varepsilon^2 p_0(\varepsilon z + ia)}, \tau, \mu, \varepsilon \right) = \frac{1}{z^2} \left(\frac{1}{2} \sin\tau + w^2 z^4 \cos\tau \right) (1 + O(\varepsilon z))$$

and consequently,

$$\mathcal{H}_1(z, w, \tau, \mu) = \frac{1}{z^2} \left(\frac{1}{2} \sin\tau + w^2 z^4 \cos\tau \right).$$

Obviously, in this case, $\ell = 2r$, $Q_0(\tau) = \tfrac{1}{2} \sin\tau + \cos\tau$ and hence $F_0(\tau) = -\tfrac{1}{2} \cos\tau + \sin\tau$, $Q_1(\tau) = 2 \cos\tau$ and $Q_2(\tau) = \cos\tau$. We have that $Q_1(\tau) \neq 0$ and $\langle F_0 \cdot Q_2 \rangle = -\tfrac{1}{4}$.

4. Solutions of the Hamilton–Jacobi equation

In this section we prove theorem 3.1. To do so we look for solutions of the Hamilton–Jacobi equation (3.3):

$$\partial_\tau \phi^\pm + \mathcal{H}(z, \partial_z \phi^\pm, \tau) = 0 \tag{4.1}$$

of the form

$$\phi^\pm(z, \tau) = \phi_0(z) + \mu \phi_1^\pm(z, \tau) + \xi^\pm, \qquad \xi^\pm \in \mathbb{C}. \tag{4.2}$$

where $\phi_0(z) = -1/((2r - 1)z^{2r-1})$ with the condition that, given $\gamma > 0$, $0 < b < b_0$ and ρ big enough, $\phi_1^\pm$ is analytic on $\mathcal{D}_{\gamma,\rho,b}^\pm$, 2π-periodic with respect to τ and $\sup_{(z,\tau)\in\mathcal{D}_{\gamma,\rho,b}^\pm} |z^{\ell+1} \partial_z \phi_1^\pm(z, \tau)| < \infty$.

We observe that both $\pm\phi_0$ are solutions of equation (4.1) for $\mu = 0$, but since, by remark 2.2, the homoclinic orbit of $H_{0,\varepsilon}$ can be approximated by $(z, \partial_z \phi_0)$ in the (z, w) variables we choose the + sign.

Below we split the proof of theorem 3.1 into five steps which are developed in sections 4.1–4.5.

Our strategy for proving theorem 3.1 will be to apply a suitable version of the fixed point equation. For that first we define the Banach space we will work with. Actually, such Banach spaces are functional spaces of Fourier series having Fourier coefficients with potential decay when $|z| \to \infty$. The precise definition and properties of these Banach spaces are given in section 4.1.

In section 4.2 we deduce a partial differential equation for both $\varphi^\pm := \partial_z \phi_1^\pm$. Such an equation can be expressed in the form

$$\partial_\tau \varphi^\pm + \partial_z \varphi^\pm = F(\varphi^\pm) \tag{4.3}$$

with F a known analytic function.

Clearly the operator $\mathcal{L}(\psi) = \partial_\tau \psi + \partial_z \psi$ is not bijective but has left-side inverse in the Banach spaces introduced above, which are studied in section 4.3. We denote them by $\mathcal{B}^\pm$.

In section 4.4, we prove that the fixed point equations $\psi = \mathcal{B}^\pm(F(\psi))$ deduced from equation (4.3) have two solutions $\varphi^\pm$ (one for the + case and another one for the − case) such that $\sup_{(z,\tau)\in\mathcal{D}_{\gamma,\rho,b}^\pm} |z^{\ell+1} \varphi^\pm(z, \tau)|$ is bounded.

Finally it only remains to show that there exist solutions $\phi^\pm$ of the initial equation (4.1) such that $\partial_z \phi^\pm = \partial_z \phi_0 + \mu \varphi^\pm$. This is done in section 4.5.

We denote by $\langle \cdot \rangle$ the mean with respect to τ.

4.1. The Banach spaces: definition and properties

This subsection is devoted to introducing the Banach spaces that we will deal with. We also state some of their useful properties.

On the one hand, we observe that all the 2π-periodic with respect to τ solutions of the unperturbed Hamilton–Jacobi equation $\partial_\tau \phi + \mathcal{H}_0(z, \partial_z \phi) = 0$ going to 0 as $|z|$ goes to ∞, do not depend on τ and they satisfy that $\partial_z \phi(z) = \pm z^{-2r}$. On the other hand we are looking for 2π-periodic solutions of the Hamilton–Jacobi equation (2.2); hence we will consider spaces of Fourier series with Fourier coefficients having potential decay to 0 as $|z| \to \infty$.

Now we give a precise definition of our Banach spaces.

For $\nu \in \mathbb{R}$ and $\gamma, \rho > 0$, we write $\overline{D}_{\gamma,\rho}^\pm = D_{\gamma,\rho}^\pm \times B(\mu_0)$, with $D_{\gamma,\rho}^\pm$ defined in (3.1), and we define the functional spaces

$$X_\pm^\nu = \{h : \overline{D}_{\gamma,\rho}^\pm \to \mathbb{C} : h \text{ is analytic and} \sup_{(z,\mu)\in\overline{D}_{\gamma,\rho}^\pm} |z^\nu h(z, \mu)| < +\infty\}.$$

It is clear that $X_\pm^\nu$ equipped with the norm

$$\|h\|_\nu = \sup_{(z,\mu) \in \overline{D}_{\gamma,\rho}^\pm} |z^\nu h(z,\mu)| \tag{4.4}$$

is a Banach space.

Now we define the space $\mathcal{X}_{\gamma,\rho,b}^{\nu,\pm}$ of Fourier series with coefficients in $X_\pm^\nu$. That is, a function $f : D_{\gamma,\rho}^\pm \times S_b \times B(\mu_0) \to \mathbb{C}$ belongs to $\mathcal{X}_{\gamma,\rho,b}^{\nu,\pm}$ if and only if

(i) f is analytic on $D_{\gamma,\rho}^\pm \times S_b \times B(\mu_0)$.
(ii) f is 2π-periodic with respect to its second variable.
(iii) Let f_k be the k-Fourier coefficient of f. We ask f_k to satisfy:

$$f_k \in X_\pm^\nu \qquad \text{and} \qquad \sum_{k \in \mathbb{Z}} \|f_k\|_\nu e^{|k|b} < +\infty.$$

We endow $\mathcal{X}_{\gamma,\rho,b}^{\nu,\pm}$ with the norm

$$\|f\|_{\mathcal{X}_{\gamma,\rho,b}^{\nu,\pm}} = \sum_{k \in \mathbb{Z}} \|f_k\|_\nu e^{|k|b}$$

and it becomes a Banach space. The proof of this fact can be found in [23].

We will write $\mathcal{X}_{\gamma,\rho,b}^\nu = \mathcal{X}_{\gamma,\rho,b}^{\nu,\pm}$ when we will state common properties of both Banach spaces. If there is no danger of confusion about the definition domain $D_{\gamma,\rho}^\pm \times S_b \times B(\mu_0)$, we will denote

$$\| \cdot \|_{\nu,b} = \| \cdot \|_{\mathcal{X}_{\gamma,\rho,b}^\nu}, \qquad \text{and} \qquad \mathcal{X}^\nu = \mathcal{X}_{\gamma,\rho,b}^\nu.$$

Remark 4.1. We emphasize that checking that a 2π-periodic function f belongs to $\mathcal{X}^\nu$ is equivalent to proving that it is analytic with respect to μ, that the k-Fourier coefficient belongs to $X_\pm^\nu$ for $k \in \mathbb{Z}$ and that $\|f\|_{\nu,b} < +\infty$. In other words the analyticity with respect to τ is an immediate consequence of (ii) and (iii).

Remark 4.2. Assume that $f \in \mathcal{X}^\nu$. We denote its k-Fourier coefficient by f_k. We note that

$$\sup_{(z,\tau,\mu) \in \mathcal{D}_{\gamma,\rho,b}^\pm} |z^\nu f(z,\tau,\mu)| \leqslant \sum_{k \in \mathbb{Z}} |z^\nu f_k(z,\mu) e^{k\tau}| \leqslant \|f\|_{\nu,b}.$$

Conversely, if $f : D_{\gamma,\rho}^\pm \times S_{b'} \times B(\mu_0) \to \mathbb{C}$ is an analytic function, satisfying that $\sup_{(z,\tau,\mu) \in \mathcal{D}_{\gamma,\rho,b'}^\pm} |z^\nu f(z,\tau,\mu)| < +\infty$, then for all $b < b'$, $f \in \mathcal{X}_{\gamma,\rho,b}^\nu$. This fact follows from the estimate

$$\|f_k\|_\nu \leqslant \sup_{(z,\tau,\mu) \in \mathcal{D}_{\gamma,\rho,b}^\pm} |z^\nu f(z,\tau,\mu)| e^{-|k|b''}, \qquad \text{for } b < b'' < b'$$

which is obtained by using the equality

$$f_k(z,\mu) = \frac{1}{2\pi} \int_0^{2\pi} f(z,\tau,\mu) e^{-ik\tau} \, d\tau = e^{-|k|b''} \frac{1}{2\pi} \int_0^{2\pi} f(z, \tau \pm ib'', \mu) e^{-ik\tau} \, d\tau,$$

taking the $+$ sign if $k < 0$ and if $k \geqslant 0$, we choose the $-$ sign.

The next lemma provides fundamental properties of the Banach spaces $\mathcal{X}^\nu$.

Lemma 4.3. *Let $\gamma, \rho, b > 0$ and $\nu, \eta \in \mathbb{R}$.*

(i) If $\nu \geqslant \eta$, $\mathcal{X}^\nu \subset \mathcal{X}^\eta$. Moreover denoting $a_\gamma = (1 + \gamma^2)^{-1/2}$

$$\|h\|_{\eta,b} \leqslant (\rho a_\gamma)^{\eta-\nu} \|h\|_{\nu,b}, \qquad \text{if } h \in \mathcal{X}^\nu. \tag{4.5}$$

(ii) If $h \in \mathcal{X}^\nu$ and $g \in \mathcal{X}^\eta$, the product $hg \in \mathcal{X}^{\nu+\eta}$ and

$$\|hg\|_{\nu+\eta,b} \leqslant \|h\|_{\nu,b}\|g\|_{\eta,b}. \tag{4.6}$$

(iii) If $h \in \mathcal{X}^\nu_{\gamma,\rho,b}$, then there exists a constant $A_{\gamma,\nu}$ such that for $l \in \mathbb{N}\{0\}$ we have that

$$\partial_z^l h \in \mathcal{X}^{l+\nu}_{2\gamma,4\rho,b} \qquad \text{and} \qquad \|\partial_z^l h\|_{l+\nu,b} \leqslant l!C_\gamma^{-l}A_{\gamma,\nu}\|h\|_{\mathcal{X}^\nu_{\gamma,\rho,b}}. \tag{4.7}$$

Proof. We observe that, if $z \in D^\pm_{\gamma,\rho}$, then $|z| \geqslant \rho(1+\gamma^2)^{-1/2}$ and therefore, formula (4.5) follows easily from the definition of the norms.

Now we check (ii). Let $h \in \mathcal{X}^\nu$ and $g \in \mathcal{X}^\eta$. We denote by h_k, g_k and $(hg)_k$ the k-Fourier coefficients of h, g and hg respectively. It is clear that, for $z \in D^\pm_{\gamma,\rho}$,

$$|z^{\nu+\eta}(hg)_k(z)| \leqslant \sum_{i\in\mathbb{Z}} |z^\nu h_i(z)||z^\eta g_{k-i}(z)| \leqslant \sum_{i\in\mathbb{Z}} \|h_i\|_\nu \|g_{k-i}\|_\eta < +\infty.$$

Therefore, since $|k| \leqslant |k-i| + |i|$,

$$\|hg\|_{\nu+\eta,b} \leqslant \sum_{k,i\in\mathbb{Z}} \|h_i\|_\nu \|g_{k-i}\|_\eta e^{|k|b} \leqslant \|h\|_{\nu,b}\|g\|_{\eta,b}$$

and we obtain bound (4.6).

Finally we prove (iii). Let $l \in \mathbb{N}\setminus\{0\}$. It is clear that $\partial_z^l h$ satisfies conditions (i) and (ii) of the definition of the Banach spaces $\mathcal{X}^{l+\nu}_{2\gamma,4\rho,b}$. To checking condition (iii), we introduce the constant $C_\gamma = \gamma\big(4(1+\gamma^2)^{1/2}(1+4\gamma^2)^{1/2}\big)^{-1} < 1/4$. Geometric arguments allow us to deduce that

$$\{u \in \mathbb{C} : |u-z| \leqslant C_\gamma|z|\} \subset D^\pm_{\gamma,\rho}, \qquad \text{if } z \in D^\pm_{2\gamma,4\rho}. \tag{4.8}$$

Let h_k be the k-Fourier coefficient of h. By Cauchy's formula,

$$|\partial_z^l h_k(z)| \leqslant \frac{l!}{2\pi|z|^l C_\gamma^l}\int_0^{2\pi} |h_k(z+|z|C_\gamma e^{i\theta})|\,d\theta \leqslant \frac{\|h_k\|_\nu l!}{|z|^{l+\nu}C_\gamma^l \max\{(1+C_\gamma)^\nu,(1-C_\gamma)^\nu\}},$$

for $z \in D^\pm_{2\gamma,4\rho}$ and hence, summing the corresponding Fourier series, we deduce (4.7). ∎

The following lemma deals with the composition of functions belonging to the spaces $\mathcal{X}^\kappa$ and $\mathcal{X}^\nu$ of the form $F(z+\mu f(z,\tau),\tau)$.

Lemma 4.4. *Let $\gamma, \rho, b > 0$, $\nu \in \mathbb{R}$ and $\kappa > -1$. We fix $F \in \mathcal{X}^\nu_{\gamma,\rho,b}$ and $f \in \mathcal{X}^\kappa_{\gamma,\rho,b}$.*
Assume that ρ satisfies the inequality

$$\mu_0 C_\gamma^{-1}\|f\|_{\mathcal{X}^\kappa_{\gamma,\rho,b}} \leqslant \frac{1}{2}\left(\frac{\rho}{(1+\gamma^2)^{1/2}}\right)^{\kappa+1} \tag{4.9}$$

with C_γ satisfying property (4.8). We define the formal expression

$$\mathcal{T}_F(f)(z,\tau) = \sum_{l\geqslant 1}\frac{1}{l!}\partial_z^l F(z,\tau)\mu^l f^l(z,\tau). \tag{4.10}$$

Then there exists a constant $B_{\gamma,\nu}$ such that

$$\mathcal{T}_F(f) \in \mathcal{X}^{\nu+\kappa+1}_{2\gamma,4\rho,b}, \qquad \|\mathcal{T}_F(f)\|_{\nu+\kappa+1,b} \leqslant \mu_0 B_{\gamma,\nu}\|F\|_{\mathcal{X}^\nu_{\gamma,\rho,b}}\|f\|_{\mathcal{X}^\kappa_{\gamma,\rho,b}}. \tag{4.11}$$

Moreover, the function $\tilde{F}(z,\tau) = F(z+\mu f(z,\tau),\tau)$ belongs to $\mathcal{X}^\nu_{2\gamma,4\rho,b}$.

Proof. We fix $\gamma, b, \rho, \nu > 0$ and $\kappa > -1$. From now on we will denote $\mathcal{X}_{2\gamma,4\rho,b}^{\eta}$ simply by $\mathcal{X}^{\eta}$ and consequently we will write $\|\cdot\|_{\eta,b} = \|\cdot\|_{\mathcal{X}_{2\gamma,4\rho,b}^{\eta}}$.

Given $F \in \mathcal{X}_{\gamma,\rho,b}^{\nu}$, by (iii) of lemma 4.3, we get that for all $l \in \mathbb{N}\backslash\{0\}$

$$\partial_z^l F \in \mathcal{X}^{l+\nu} \qquad \text{and} \qquad \|\partial_z^l F\|_{l+\nu,b} \leqslant l! C_\gamma^{-l} A_{\gamma,\nu} \|F\|_{\mathcal{X}_{\gamma,\rho,b}^{\nu}}. \tag{4.12}$$

Let now $f \in \mathcal{X}_{\gamma,\rho,b}^{\kappa} \subset \mathcal{X}^{\kappa}$. Since $\kappa + 1 > 0$, by (ii) lemma 4.3 and property (4.12), we have that $\partial_z^l F \cdot f^l \in \mathcal{X}^{l(\kappa+1)+\nu} \subset \mathcal{X}^{\kappa+1+\nu}$. Denoting $\rho_\gamma = \rho(1+\gamma^2)^{-1/2}$ and using again lemma 4.3, we have that

$$\|\partial_z^l F \cdot f^l\|_{\kappa+1+\nu,b} \leqslant \rho_\gamma^{(-l+1)(\kappa+1)} \|\partial_z^l F\|_{l+\nu,b} \|f\|_{\kappa,b}^l$$

$$\leqslant l! A_{\gamma,\nu} C_\gamma^{-1} (\rho_\gamma^{\kappa+1} C_\gamma)^{-l+1} \|F\|_{\mathcal{X}_{\gamma,\rho,b}^{\nu}} \|f\|_{\kappa,b}^l.$$

Then we have that $\mathcal{T}_F(f)$ is a series of functions belonging to $\mathcal{X}^{\kappa+1+\nu}$. Moreover, since ρ satisfies condition (4.9) and $\|f\|_{\kappa,b} \leqslant \|f\|_{\mathcal{X}_{\gamma,\rho,b}^{\kappa}}$, the constant ρ_γ satisfies $\rho_\gamma^{-\kappa-1} \mu_0 C_\gamma^{-1} \|f\|_{\kappa,b} \leqslant 1/2$ and therefore we have that

$$\|\mathcal{T}_F(f)\|_{\kappa+1+\nu,b} \leqslant \sum_{l \geqslant 1} \frac{1}{l!} |\mu|^l \|\partial_z^l F \cdot f^l\|_{\kappa+1+\nu,b}$$

$$\leqslant A_{\gamma,\nu} C_\gamma^{-1} \|F\|_{\mathcal{X}_{\gamma,\rho,b}^{\nu}} \sum_{l \geqslant 1} (\rho_\gamma^{\kappa+1} C_\gamma)^{-l+1} \mu_0^l \|f\|_{\kappa,b}^l$$

$$\leqslant 2 A_{\gamma,\nu} C_\gamma^{-1} \mu_0 \|F\|_{\mathcal{X}_{\gamma,\rho,b}^{\nu}} \|f\|_{\mathcal{X}_{\gamma,\rho,b}^{\kappa}} \tag{4.13}$$

and property (4.11) is proved.

Finally, we note that since the condition (4.9) is fulfilled by f and ρ, by remark 4.2,

$$|\mu f(z,\tau)| \leqslant |z|^{-\kappa} \mu_0 \|f\|_{\nu,b} \leqslant |z| \rho_\gamma^{-\kappa-1} \mu_0 \|f\|_{\mathcal{X}_{\gamma,\rho,b}^{\nu}} < C_\gamma |z|.$$

Hence by property (4.8), $z + \mu f(z,\tau) \in D_{\gamma,\rho}$ for all $(z,\tau) \in D_{2\gamma,4\rho}^{\pm} \times S_b$. Then it is clear that, by Taylor's theorem $\tilde{F} = F + \mathcal{T}_F(f)$ and therefore by (4.11), $\tilde{F} \in \mathcal{X}^{\nu}$ provided $\mathcal{T}_F(f) \in \mathcal{X}^{\kappa+1+\nu} \subset \mathcal{X}^{\nu}$. ∎

From now on we deal only with the $+$ case, the $-$ case being analogous. For this reason we will skip the $+$ sign of our notation in the remaining part of this section.

4.2. The partial differential equation $\partial_z \phi_1$ satisfies

Since ϕ_0 is a solution of equation (3.3), for $\mu = 0$, $\phi = \phi_0 + \mu\phi_1$ will be solutions of the Hamilton–Jacobi equation (3.3) if and only if ϕ_1 satisfy the equation:

$$\partial_\tau \phi_1 + \partial_z \phi_1 + \mathcal{H}_1(z, \partial_z \phi_0 + \mu \partial_z \phi_1, \tau) + \frac{\mu}{2} z^{2r} (\partial_z \phi_1)^2 = 0. \tag{4.14}$$

In order to shorten the notation, we introduce

$$Q_j(\tau) = \sum_{k=j}^{N} \binom{k}{j} A_k(\tau), \qquad \chi_1^{\ell}(z, \tau) = -\frac{\ell}{z^{\ell+1}} Q_0(\tau), \tag{4.15}$$

$$\chi_2^{\ell}(z, w, \tau) = \frac{1}{z^{\ell}} Q_1(\tau) \mu z^{2r} w, \qquad \chi_3^{\ell}(z, w, \tau) = \frac{\mu}{2} z^{2r} w^2 + \frac{1}{z^{\ell}} \sum_{j=2}^{N} Q_j(\tau)(\mu z^{2r} w)^j$$

and we recall that $\{A_k\}_{k\in\{0,\ldots,N\}}$ are determined by $\mathcal{H}_1(z, w, \tau) = \sum_{k=0}^{N} A_k(\tau) w^k z^{2rk-\ell}$.

Finally, differentiating equation (4.14) with respect to z and denoting $\partial_z \phi_1$ by φ, it is not difficult to check that φ must satisfy

$$\partial_\tau \varphi + \partial_z \varphi + \chi_1^{\ell}(z, \tau) + \partial_z(\chi_2^{\ell}(z, \varphi, \tau) + \chi_3^{\ell}(z, \varphi, \tau)) = 0. \tag{4.16}$$

4.2.1. The case $\ell = 2r$. We study the particular case $\ell = 2r$. Since Q_1 has zero mean, the function determined by $\partial_\tau F_1 = Q_1$ and $\langle F_1 \rangle = 0$ is 2π-periodic. Performing the change of variables given by

$$u = z - \mu F_1(\tau), \qquad \widetilde{\varphi}(u, \tau) = \varphi(u + \mu F_1(\tau), \tau)$$

and denoting again $\widetilde{\varphi}$ by φ and u by z, equation (4.16) becomes

$$\partial_\tau \varphi + \partial_z \varphi + \chi_1^\ell(Z(z, \tau), \tau) + \partial_z(\chi_3^{2r}(Z(z, \tau), \varphi, \tau)) = 0, \tag{4.17}$$

where $Z(z, \tau) = z + \mu F_1(\tau)$.

4.2.2. The final equation for $\partial_z \phi_1$ in the case $\ell \geqslant 2r$. To write equations (4.16) and (4.17) in a unified way we introduce the functions

$$\psi_1^\ell(z, \tau) = \begin{cases} -\chi_1^\ell(z, \tau) & \text{if } \ell > 2r, \\ -\chi_1^{2r}(Z(z, \tau), \tau) & \text{if } \ell = 2r \end{cases} \tag{4.18}$$

and

$$\psi_2^\ell(\varphi)(z, \tau) = \begin{cases} -\chi_2^\ell(z, \varphi, \tau) - \chi_3^\ell(z, \varphi, \tau) & \text{if } \ell > 2r, \\ -\chi_3^{2r}(Z(z, \tau), \varphi, \tau) & \text{if } \ell = 2r. \end{cases} \tag{4.19}$$

With this notation, equations (4.16) and (4.17) become

$$\partial_\tau \varphi + \partial_z \varphi = \psi_1^\ell + \partial_z(\psi_2^\ell(\varphi)). \tag{4.20}$$

4.3. The operator $\mathcal{B}$

In this section we will study the operator $\mathcal{B}$ formally defined by

$$\mathcal{B}(h)(z, \tau) = \int_{+\infty}^0 h(z + t, \tau + t) \, dt. \tag{4.21}$$

Remark 4.5. We note that, differentiating formally under the integral sign, $\partial_\tau \mathcal{B}(h) + \partial_z \mathcal{B}(h) = h$. Hence the operator $\mathcal{B}$ is a (formal) left-inverse of $\mathcal{L}(\psi) = \partial_\tau \psi + \partial_z \psi$.

The next lemma ensures that the operator $\mathcal{B}$ is actually a left-inverse of $\mathcal{L}$ in $\mathcal{X}_{\gamma, \rho, b}^\nu$.

Lemma 4.6. *Let $\rho, \gamma, b > 0$ and $\nu > 1$. Then*

(i) *The operator $\mathcal{B} : \mathcal{X}^\nu \to \mathcal{X}^{\nu-1}$ is well defined. Moreover, there exists a constant $K_{\nu, \gamma}$ depending only on ν and γ, such that*

$$\|\mathcal{B}(h)\|_{\nu-1, b} \leqslant K_{\nu, \gamma} \|h\|_{\nu, b} \qquad \text{if } h \in \mathcal{X}^\nu.$$

(ii) *Let $h \in \mathcal{X}^\nu$. Then $\partial_z \mathcal{B}(h) \in \mathcal{X}^\nu$ and there exists a constant $C_{\nu, \gamma}$ such that*

$$\|\partial_z \mathcal{B}(h)\|_{\nu, b} \leqslant C_{\nu, \gamma} \|h\|_{\nu, b}.$$

(iii) *For $h \in \mathcal{X}^\nu$ with $\langle h \rangle = 0$, we have that $\mathcal{B}(h) \in \mathcal{X}^\nu$, $\langle \mathcal{B}(h) \rangle = 0$ and*

$$\|\mathcal{B}(h)\|_{\nu, b} \leqslant C_{\nu, \gamma} \|h\|_{\nu, b}. \tag{4.22}$$

Proof. First we observe that if $h \in \mathcal{X}^\nu$, for all $(z, \tau) \in D_{\gamma, \rho} \times S_b$, $|h(z, \tau)| \leqslant |z|^{-\nu} \|h\|_{\nu, b}$. Therefore, if $\nu > 1$, using Fubbini's theorem, we can express the k-Fourier coefficient of $\mathcal{B}(h)$ as

$$(\mathcal{B}(h))_k(z) = \int_{+\infty}^0 e^{ikt} h_k(z + t) \, dt, \tag{4.23}$$

where h_k denotes the k-Fourier coefficient of h.

We fix $\rho, \gamma, b > 0$, $\nu > 1$ and $h \in \mathcal{X}^\nu$. First we deal with (i). On the one hand,

$$\int_0^{+\infty} \frac{1}{|z+t|^\nu}\,\mathrm{d}t \leqslant K_{\nu,\gamma} \frac{1}{|z|^{\nu-1}} \qquad \text{if } z \in D_{\gamma,\rho}, \tag{4.24}$$

where $K_{\nu,\gamma} = 2(1 + \gamma^2)^{(\nu-1)/2} \gamma^{1-\nu} \int_0^{+\infty} (1 + t^2)^{-\nu/2}\,\mathrm{d}t$. Bound (4.24) is straightforward by using the fact that if $\mathrm{Re}\,z < 0$ and $z \in D_{\gamma,\rho}$, $\gamma|z| \leqslant (1 + \gamma^2)^{1/2}|\mathrm{Im}z|$. The case $\mathrm{Re}\,z \geqslant 0$ is obvious.

On the other hand, using $|h_k(z+t)| \leqslant \|h_k\|_\nu |z+t|^{-\nu}$ in equation (4.23) and applying bound (4.24) we deduce

$$|(\mathcal{B}(h))_k(z)| \leqslant \|h_k\|_\nu \int_0^{+\infty} \frac{1}{|z+t|^\nu}\,\mathrm{d}t \leqslant K_{\nu,\gamma}\|h_k\|_\nu \frac{1}{|z|^{\nu-1}}, \qquad \text{if } z \in D_{\gamma,\rho}.$$

Hence $\|(\mathcal{B}(h))_k\|_{\nu-1} \leqslant K_{\nu,\gamma}\|h_k\|_\nu$ and by using the definition of $\|\cdot\|_{\nu,b}$ we conclude that $\|\mathcal{B}(h)\|_{\nu-1,b} \leqslant K_{\nu,\gamma}\|h\|_{\nu,b}$.

Before checking (ii) and (iii) we claim that if $h \in \mathcal{X}^\nu$,

$$\|(\mathcal{B}(h))_k\|_\nu \leqslant \tilde{C}_{\nu,\gamma}|k|^{-1}\|h_k\|_\nu \qquad \text{for } k \in \mathbb{Z}\backslash\{0\} \tag{4.25}$$

with $\tilde{C}_{\nu,\gamma} = (\sin\tilde{\gamma})^{-\nu-1}$ and $\tilde{\gamma} = (\arctan\gamma/2)$. Indeed, we fix $k > 0$ and $z \in D_{\gamma,\rho}$. Clearly, $z + t\mathrm{e}^{\mathrm{i}\tilde{\gamma}} \in D_{\gamma,\rho}$, for $t \geqslant 0$. Then, since h_k is analytic in $D_{\gamma,\rho}$ and $\lim_{\mathrm{Re}\,z\to+\infty} zh_k(z) = 0$, Cauchy's theorem implies that we can move the path of integration $z + t$ to $z + t\mathrm{e}^{\mathrm{i}\tilde{\gamma}}$:

$$(\mathcal{B}^+(h))_k(z) = \int_{+\infty}^0 \mathrm{e}^{\mathrm{i}kt} h_k(z+t)\,\mathrm{d}t = \int_{+\infty}^0 \mathrm{e}^{\mathrm{i}kt\mathrm{e}^{\mathrm{i}\tilde{\gamma}}} h_k(z + t\mathrm{e}^{\mathrm{i}\tilde{\gamma}})\mathrm{e}^{\mathrm{i}\tilde{\gamma}}\,\mathrm{d}t. \tag{4.26}$$

On the other hand, using the fact that $\arg(z) \in (-\pi + \arctan\gamma, \pi - \arctan\gamma)$, it is easy to check that $|z + t\mathrm{e}^{\mathrm{i}\tilde{\gamma}}| \geqslant |z|\sin\tilde{\gamma}$ and therefore, bounding the last integral in equation (4.26),

$$|(\mathcal{B}(h))_k(z)| \leqslant \|h_k\|_\nu \int_0^{+\infty} \frac{\mathrm{e}^{-kt\sin\tilde{\gamma}}}{|z + t\mathrm{e}^{\mathrm{i}\tilde{\gamma}}|^\nu}\,\mathrm{d}t \leqslant \|h_k\|_\nu \frac{1}{|k||z|^\nu(\sin\tilde{\gamma})^{\nu+1}}. \tag{4.27}$$

In the same way, if $k < 0$, we choose the path of integration $t = s\mathrm{e}^{-\mathrm{i}\tilde{\gamma}}$, $s \geqslant 0$ in equation (4.23) and we obtain the same bound as in (4.27). This proves bound (4.25).

Next we prove (ii). We have already seen that $\mathcal{B}(h) \in \mathcal{X}^{\nu-1}$. Therefore, integrating by parts in equation (4.23), we obtain an expression for the k-Fourier coefficient of $\partial_z\mathcal{B}(h)$ which is $\partial_z(\mathcal{B}(h))_k = h_k - \mathrm{i}k(\mathcal{B}(h))_k$. Now bound (4.25) implies (ii):

$$\|\partial_z\mathcal{B}(h)\|_{\nu,b} \leqslant \|h\|_{\nu,b} + \sum_{k \in \mathbb{Z}\backslash\{0\}} |k|\|(\mathcal{B}(h))_k\|_\nu \mathrm{e}^{|k|b} \leqslant (1 + \tilde{C}_{\nu,\gamma})\|h\|_{\nu,b}.$$

To check (iii) is straightforward. Indeed, by (4.23), if $h_0 = \langle h \rangle = 0$, then $\langle \mathcal{B}(h) \rangle = 0$. Finally, bound (4.22) follows from (4.25). ∎

Remark 4.7. Given $\nu > 1$ and $h \in \mathcal{X}^\nu$, if ψ is a solution of $\mathcal{L}(\psi) = h$ such that $\lim_{\mathrm{Re}\,z\to+\infty} \psi(z,\tau) = 0$, then $\psi = \mathcal{B}(h)$.

Indeed, let ψ be a solution of $\mathcal{L}(\psi) = h$. By lemma 4.6, $\mathcal{B}(h)$ is a solution of $\mathcal{L}(\psi) = h$; thus there exists a function χ such that $\psi = \mathcal{B}(h) + \chi(z - \tau)$. Moreover, since ψ and $\mathcal{B}(h)$ are 2π-periodic with respect to τ and they both satisfy $\lim_{\mathrm{Re}\,z\to+\infty} \psi(z,\tau) = \lim_{\mathrm{Re}\,z\to+\infty} \mathcal{B}(h)(z,\tau) = 0$, the function χ is 2π-periodic and it also satisfies that $\lim_{\zeta\to\infty} \chi(\zeta) = 0$. This implies that $\chi \equiv 0$.

4.4. Existence, uniqueness and asymptotic properties of $\partial_z \phi_1$

We have seen in section 4.2 that $\varphi := \partial_z \phi_1$ has to be a solution of the partial differential equation (4.16). This subsection is devoted to proving that equation (4.16) has only one solution with the properties required for $\partial_z \phi_1$. Concretely we will prove the following.

Proposition 4.8. *Let $\gamma > 0$ and $0 < b < b_0$. If $\ell \geqslant 2r$, there exists ρ_0 depending on γ, b, r and ℓ, such that the partial differential equation (4.16) has only one solution φ 2π-periodic with respect to τ and with the asymptotic property $\lim_{\mathrm{Re}\, z \to +\infty} \varphi(z, \tau) = 0$. Moreover $\varphi \in \mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$ and $\varphi - \mathcal{B}(\psi_1^\ell) \in \mathcal{X}^{\ell+1+\eta_\ell}$ with $\eta_\ell = \ell - 2r$ if $\ell > 2r$ and $\eta_\ell = 1$ if $\ell = 2r$.*

Let us consider equation (4.20).

$$\partial_\tau \varphi + \partial_z \varphi = \psi_1^\ell + \partial_z \big(\psi_2^\ell(\varphi) \big).$$

(We recall that $\{\psi_i^\ell\}_{i=1,2}$ were defined by formulae (4.18) and (4.19)). We also stress that equation (4.20) was deduced from equation (4.16) simply by performing a change of variables if $\ell = 2r$. If $\ell > 2r$ both equations are the same.

We observe that equation (4.20) can be (formally) written as a fixed point equation. Indeed, we only need to take into account that the operator $\mathcal{B}$ is linear and by remark 4.5, $\mathcal{B} = \mathcal{L}^{-1}$. Moreover $\mathcal{B} \circ \partial_z = \partial_z \circ \mathcal{B}$ (differentiating formally under the integral sign). Hence equation (4.20) can be formally expressed as

$$\varphi = \mathcal{B}(\psi_1^\ell) + \partial_z \mathcal{B}(\psi_2^\ell(\varphi)). \tag{4.28}$$

To prove proposition 4.8 we perform two steps. The first is devoted to proving that equation (4.28) has a fixed point φ belonging to $\mathcal{X}_{\gamma, \tilde{\rho}_0, b}^{\ell+1}$ with $\tilde{\rho}_0$ large enough.

Later we will check that φ is a solution of equation (4.20) provided that (after restricting our definition domain $D_{\gamma, \tilde{\rho}_0, b}$ if necessary) the linear operators ∂_z and $\mathcal{B}$ actually commute. Note that this fact implies that equation (4.28) is equivalent to

$$\varphi = \mathcal{B}\big(\psi_1^\ell + \partial_z(\psi^\ell(\varphi)) \big)$$

and hence by remark 4.5, φ is a solution of equation (4.20). The uniqueness of this solution comes from remark 4.7.

Finally, taking into account the relation between equations (4.20) and (4.16) we will conclude that φ is a solution of equation (4.16) if $\ell > 2r$. If $\ell = 2r$, we will need to perform the change of coordinates given by $\tilde{\varphi}(z, \tau) = \varphi(z - \mu F_1(\tau), \tau)$, with F_1 a suitable periodic function, to obtain the solution of equation (4.16) that we are looking for.

4.4.1. The fixed point equation.
Before dealing with fixed point equation (4.28), we state an auxiliary lemma which works in a more general setting.

Lemma 4.9. *We fix $\gamma, b, \rho > 0$, $\nu > 1$ and $h_0 \in \mathcal{X}^\nu$ and we define $R_0 = 8\|h_0\|_{\nu, b} + 1/2$. We denote by $B(R)$ the open ball of $\mathcal{X}^\nu$ of radius $R > 0$ and centred at the origin.*

Let $\mathcal{R}$ be an analytic operator $\mathcal{R} : B(R_0) \to \mathcal{X}^0$ such that there exist $C, \eta > 0$ satisfying

$$\mathcal{R}(0) = 0, \qquad \partial_h^j \mathcal{R}(0) \in \mathcal{X}^{\eta-(j-1)\nu} \qquad \text{and} \qquad \|\partial_h^j \mathcal{R}(0)\|_{\eta-(j-1)\nu, b} \leqslant C \frac{j!}{(2R_0)^j}, \qquad \text{for } j \geqslant 1.$$

Then there exists $\rho_1 = \rho_1(\gamma, b, \nu, \eta, \rho)$ big enough such that the operator

$$\mathcal{F}(h) := h_0 + \partial_z \mathcal{B}(\mathcal{R}(h))$$

has a fixed point $h \in \mathcal{X}_{\gamma, \rho_1, b}^\nu$.

Proof. To shorten the notation, along this proof we will denote $\mathcal{X}^{\nu}_{\gamma,\rho_1,b}$ and $\|\cdot\|_{\mathcal{X}^{\nu}_{\gamma,\rho_1,b}}$ simply by $\mathcal{X}^{\nu}$ and $\|\cdot\|_{\nu,b}$, respectively.

We take $\rho_1 = \max\{\rho, (1+\gamma^2)^{1/2}(16CR_0^{-1}C_{\nu,\gamma})^{1/\eta}\}$ where $C_{\nu,\gamma}$ is the constant defined in (ii) of lemma 4.6. This choice will be justified below.

In [1] it was proved that if f is an analytic operator defined in a complex Banach space, satisfying that $f(B(R)) \subset B(\theta R)$ for some $\theta < 1/2$, then f has a unique fixed point belonging to $B(\theta R)$. Since the operator $\mathcal{F}$ is analytic, we are allowed to use this result. Specifically we will see that $\mathcal{F}(B(R_0)) \subset B(R_0/4)$.

We fix $h \in B(R_0)$. We claim that,

$$\mathcal{R}(h) \in \mathcal{X}^{\nu+\eta} \qquad \text{and} \qquad \|\mathcal{R}(h)\|_{\nu+\eta,b} \leqslant C \tag{4.29}$$

with C the constant given in lemma 4.9. Indeed, since $\mathcal{R}$ is analytic and $\mathcal{R}(0) = 0$, we have that, formally

$$\mathcal{R}(h) = \sum_{j \geqslant 1} \partial_h^j \mathcal{R}(0) \frac{h^j}{j!}.$$

Since $\partial_h^j \mathcal{R}(0) \in \mathcal{X}^{\eta-(j-1)\nu}$, using the fact that $h \in B(R_0) \subset \mathcal{X}^{\nu}$ and (ii) of lemma 4.3, we have that for all $j \geqslant 1$, $\partial_h^j \mathcal{R}(0)h^j \in \mathcal{X}^{\eta-(j-1)\nu+j\nu} = \mathcal{X}^{\eta+\nu}$ and moreover, taking into account that $\|h\|_{\nu,b} \leqslant R_0$ and $\|\partial_h^j \mathcal{R}(0)\|_{\eta-(j-1)\nu,b} \leqslant \|\partial_h^j \mathcal{R}(0)\|_{\mathcal{X}^{\eta-(j-1)\nu}_{\gamma,\rho,b}} \leqslant Cj!(2R_0)^{-j}$,

$$\|\partial_h^j \mathcal{R}(0)h^j\|_{\eta+\nu,b} \leqslant \|\partial_h^j \mathcal{R}(0)\|_{\eta-(j-1)\nu,b}\|h\|_{\nu,b}^j \leqslant Cj!\frac{1}{2^j}.$$

Hence, $\mathcal{R}(h) \in \mathcal{X}^{\nu+\eta}$ and

$$\|\mathcal{R}(h)\|_{\nu+\eta,b} \leqslant \sum_{j \geqslant 1} C2^{-j} = C.$$

This proves property (4.29).

On the one hand, we observe that, $\mathcal{R}(h) \in \mathcal{X}^{\nu+\eta} \subset \mathcal{X}^{\nu}$, therefore, by property (4.29) and (i) of lemma 4.3 we obtain

$$\|\mathcal{R}(h)\|_{\nu,b} \leqslant \rho_1^{-\eta}(1+\gamma^2)^{\eta/2}\|\mathcal{R}(h)\|_{\nu+\eta,b} \leqslant C\rho_1^{-\eta}(1+\gamma^2)^{\eta/2}. \tag{4.30}$$

On the other hand, since $\mathcal{R}(h) \in \mathcal{X}^{\nu}$, we deduce that $\partial_z \mathcal{B}(\mathcal{R}(h)) \in \mathcal{X}^{\nu}$ using (ii) of lemma 4.6, and hence $\mathcal{F}(h) \in \mathcal{X}^{\nu}$. Again by (ii) of lemma 4.6, we can bound the norm of $\partial_z \mathcal{B}(\mathcal{R}(h))$ and finally using the definitions of R_0 and ρ_1 and bound (4.30) of $\|\mathcal{R}(h)\|_{\nu,b}$, we obtain that

$$\|\mathcal{F}(h)\|_{\nu,b} \leqslant \|h_0\|_{\nu,b} + \|\partial_z \mathcal{B}(\mathcal{R}(h))\|_{\nu,b} \leqslant \frac{R_0}{8} + C_{\nu,\gamma}C\rho_1^{-\eta}(1+\gamma^2)^{\eta/2} \leqslant \frac{R_0}{8} + \frac{R_0}{16} < \frac{R_0}{4}$$

and the lemma is proved. ∎

Lemma 4.10. *For any $\gamma > 0$, $0 < b < b_0$, there exists $\tilde{\rho}_0 = \tilde{\rho}_0(\gamma, b, \ell, r)$ such that the fixed point equation*

$$\varphi = \mathcal{F}^{\ell}(\varphi) := \mathcal{B}(\psi_1^{\ell}) + \partial_z \mathcal{B}(\psi_2^{\ell}(\varphi)) \tag{4.31}$$

has a solution $\varphi \in \mathcal{X}^{\ell+1}_{\gamma,\tilde{\rho}_0,b}$. Moreover $\psi_2^{\ell}(\varphi) \in \mathcal{X}^{\ell+1+\eta_{\ell}}_{\gamma,\tilde{\rho}_0,b}$ with $\eta_{\ell} = \ell - 2r$ if $\ell > 2r$ and $\eta_{\ell} = 1$ if $\ell = 2r$.

Proof. The notation used along this proof was introduced in section 4.2.

We fix $\gamma > 0$, $0 < b < b_0$ and $\rho = (1 + \gamma^2)^{1/2} + 8\mu_0 C_{\gamma/2}^{-1}(1 + \gamma^2)^{1/2}\|F_1\|_{0,b} > 0$. Such a choice will be justified later. We notice that since F_1 does not depend on z, $\|F_1\|_{0,b}$ is independent of ρ.

In order to prove this result, we are going to check that the hypotheses of lemma 4.9 are satisfied for $\nu = \ell + 1$, $\eta_\ell > 0$, $h_0 = \mathcal{B}(\psi_1^\ell)$ and $\mathcal{R} = \psi_2^\ell$. If the hypotheses of lemma 4.9 are fulfilled, check that $\psi_2^\ell(\varphi) \in \mathcal{X}_{\gamma,\tilde{\rho}_0,b}^{\ell+1+\eta_\ell}$ is straightforward from property (4.29).

We note that since the functions Q_j are 2π-periodic and analytic in S_{b_0}, they belong to $\mathcal{X}_{\gamma,s,b}^0$ for all $s > 0$.

First we deal with the case $\ell > 2r$ which is simpler. By definition (4.18) of ψ_1^ℓ, it is clear that $\psi_1^\ell \in \mathcal{X}^{\ell+1}$. Moreover, $\langle \psi_1^\ell \rangle = 0$. Therefore, by (iii) of lemma 4.6, $\mathcal{B}(\psi_1^\ell) \in \mathcal{X}^{\ell+1}$. As in lemma 4.9, we define $R_0 = 8\|\mathcal{B}(\psi_1^\ell)\|_{\ell+1,b} + 1/2$.

On the other hand, definition (4.19) of ψ_2^ℓ implies that it is analytic (in fact it is a polynomial in φ), $\psi_2^\ell(0) = 0$ and moreover,

$$\partial_\varphi \psi_2^\ell(0) = -\mu Q_1(\tau) z^{-\ell+2r} \in \mathcal{X}^{\ell-2r},$$

$$\partial_\varphi^2 \psi_2^\ell(0) = -\mu z^{2r} - 2\mu^2 z^{4r-\ell} Q_2(\tau) \in \mathcal{X}^{-2r} \subset \mathcal{X}^{\ell-2r-(\ell+1)}$$

$$\partial_\varphi^j \psi_2^\ell(0) = -j!\mu^j z^{2rj-\ell} Q_j(\tau) \in \mathcal{X}^{\ell-2rj} \subset \mathcal{X}^{\ell-2r-(j-1)(\ell+1)}, \qquad \text{if } 3 \leqslant j \leqslant N,$$

$$\partial_\varphi^j \psi_2^\ell(0) = 0, \qquad \text{if } j > N,$$

provided $\ell > 2r$. We also note that, since $\rho \geqslant (1 + \gamma^2)^{1/2}$, by (i) of lemma 4.3,

$$\|\partial_\varphi^j \psi_2^\ell(0)\|_{\ell-2r-(j-1)(\ell+1)} \leqslant \mu_0 + j!\mu_0^j \|Q_j\|_{0,b}, \qquad \text{if } 1 \leqslant j \leqslant N.$$

Hence, the hypotheses of lemma 4.9 are satisfied by $\mathcal{R} = \psi_2^\ell$ with $\eta_\ell = \ell - 2r$, $\nu = \ell + 1$ and $C = \max_{0 \leqslant j \leqslant N}(\mu_0 + \mu_0^j\|Q_j\|_{0,b})(2R_0)^j$.

Now we deal with the case $\ell = 2r$. First we check that $\mathcal{B}(\psi_1^{2r}) \in \mathcal{X}^{2r+1}$. Looking at definition (4.18) of ψ_1^{2r} one deduces that $\psi_1^{2r} = -\chi_1 + \mathcal{T}_{-\chi_1}(F_1)$ where χ_1 was given in definition (4.15) and $\mathcal{T}_{-\chi_1}$ is the operator defined in lemma 4.4. Hence, since $\chi_1 \in \mathcal{X}_{\gamma/2,\rho/4,b}^{2r+1}$, again using lemma 4.4, we have that $\mathcal{T}_{-\chi_1}(F_1) \in \mathcal{X}^{2r+2}$ provided that $\rho \geqslant 8\mu_0 C_{\gamma/2}^{-1}(1 + (\gamma/2)^2)^{1/2}\|F_1\|_{0,b}$. Therefore, by (i) of lemma 4.6, $\mathcal{B}(\mathcal{T}_{-\chi_1}(F_1)) \in \mathcal{X}^{2r+1}$. Finally, we observe that $\langle \chi_1 \rangle = 0$. Thus (iii) of lemma 4.6 implies that $\mathcal{B}(-\chi_1) \in \mathcal{X}^{2r+1}$ and henceforth, $\mathcal{B}(\psi_1^{2r}) \in \mathcal{X}^{2r+1}$.

Now we check that $\mathcal{R} = \psi_2^{2r}$ satisfies the hypotheses of lemma 4.9 with $\eta_\ell = 1$ and $\nu = 2r + 1$. Indeed, we note that $\psi_2^{2r}(0) = 0$ and, since $z + \mu F_1(\tau) \in \mathcal{X}^1$,

$$\partial_\varphi^1 \psi_2^{2r}(0) = 0,$$

$$\partial_\varphi^2 \psi_2^{2r}(0) = -\mu(z + \mu F_1(\tau))^{2r} - 2\mu^2(z + \mu F_1(\tau))^{2r} Q_2(\tau) \in \mathcal{X}^{1-(2r+1)},$$

$$\partial_\varphi^j \psi_2^{2r}(0) = -j!\mu^j (z + \mu F_1(\tau))^{2r(j-1)} Q_j(\tau) \in \mathcal{X}^{1-(j-1)(2r+1)} \qquad \text{if } 3 \leqslant j \leqslant N,$$

$$\partial_\varphi^j \psi_2^{2r}(0) = 0 \qquad \text{if } j > N.$$

Therefore, using the definition of ρ, we realize that

$$\|\partial_\varphi^j \psi_2^{2r}(0)\|_{1-(j-1)(2r+1)} \leqslant \left(\mu_0 + j!\mu_0^j\|Q_j\|_{0,b}\right)\left(1 + \frac{C_{\gamma/2}}{8}\right)^{2r(j-1)}, \qquad \text{if } 1 \leqslant j \leqslant N$$

and the proof is complete. ∎

4.4.2. Proof of proposition 4.8   We fix $\gamma > 0$, $0 < b < b_0$ and we define $\rho_0 = \max\{4(4 + \gamma^2)^{1/2} C_{\gamma/2}^{-1} \|F_1\|_{0,b}, 8\tilde{\rho}_0(\gamma/4, b, \ell, r)\}$, where $\tilde{\rho}_0$ was given in lemma 4.10. This choice of ρ_0 is justified by the following computations.

By lemma 4.10 the fixed point equation (4.31) has a solution $\varphi \in \mathcal{X}_{\gamma/4, \rho_0/8, b}^{\ell+1}$ such that $\varphi - \mathcal{B}(\psi_1^\ell) \in \mathcal{X}_{\gamma/4, \rho_0/8, b}^{\ell+1+\eta_\ell}$. We claim that

$$\partial_z \mathcal{B}(\psi_2^\ell(\varphi)) = \mathcal{B}(\partial_z \psi_2^\ell(\varphi)) \qquad \text{on } D_{\gamma/2, \rho_0/4} \times S_b. \tag{4.32}$$

Indeed, since $\psi_2^\ell(\varphi) \in \mathcal{X}_{\gamma/4, \rho_0/8, b}^{\ell+1+\eta_\ell}$, using (iii) of lemma 4.3 we get that $\partial_z \psi_2^\ell(\varphi) \in \mathcal{X}_{\gamma/2, \rho_0/4, b}^{\ell+2+\eta_\ell}$. Therefore, by remark 4.2,

$$|\partial_z \psi_2^\ell(\varphi)(z, \tau)| \leqslant |z|^{-\ell-2-\eta_\ell} \|\partial_z \psi_2^\ell(\varphi)\|_{\mathcal{X}_{\gamma/2, \rho_0/4}^{\ell+2+\eta_\ell}}, \qquad \text{for all } (z, \tau) \in D_{\gamma/2, \rho_0/4} \times S_b,$$

and we obtain formula (4.32) by differentiating under the integral sign $\mathcal{B}(\psi_2^\ell(\varphi))$.

Equality (4.32) implies that φ is a solution of equation $\varphi = \mathcal{B}(\psi_1^\ell) + \mathcal{B}(\partial_z \psi_2^\ell(\varphi))$ and hence, since $(\partial_\tau + \partial_z) \circ \mathcal{B} = \text{Id}$ (remark 4.5), φ is a solution of equation (4.20) belonging to $\mathcal{X}_{\gamma/2, \rho/4, b}^{\ell+1}$. Moreover, $\varphi - \mathcal{B}(\psi_1^\ell) \in \mathcal{X}_{\gamma/2, \rho_0/4, b}^{\ell+1+\eta_\ell}$.

Taking into account the relation between equations (4.20) and (4.16) given in section 4.2, clearly, if $\ell > 2r$ we deduce that φ is a solution of equation (4.16) belonging to $\mathcal{X}_{\gamma/2, \rho_0/4, b}^{\ell+1} \subset \mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$ and in this case we are done.

In the case $\ell = 2r$, the function $\widetilde{\varphi}(z, \tau) = \varphi(z - \mu F_1(\tau), \tau)$ is a solution of equation (4.16). Moreover, since $\varphi \in \mathcal{X}_{\gamma/2, \rho_0/4, b}^{2r+1}$ applying lemma 4.4 we obtain that $\widetilde{\varphi} \in \mathcal{X}_{\gamma, \rho_0, b}^{2r+1}$ provided that $\rho_0 \geqslant 4(4 + \gamma^2)^{1/2} C_{\gamma/2}^{-1} \|F_1\|_{0,b}$. We also note that, since $\tilde{\varphi} - \varphi = \mathcal{T}_\varphi(F_1) \in \mathcal{X}_{\gamma, \rho_0, b}^{2r+2}$, we have that $\varphi - \mathcal{B}(\psi_1^{2r}) \in \mathcal{X}_{\gamma, \rho_0, b}^{2r+2}$.

Finally, the uniqueness of the solution φ follows from remark 4.7.

4.5. End of the proof of theorem 3.1

Given $\gamma > 0$ and $0 < b < b_0$, let φ be the solution of equation (4.16) belonging to $\mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$, where $\rho_0 = \rho_0(\gamma, b, \ell, r)$ is the constant given by proposition 4.8.

We claim that the solutions of equation (4.14) such that their derivative with respect to z belong to $\mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$ are defined up to constant. Indeed, let ϕ^1, ϕ^2 be two solutions of (4.14). Clearly $\partial_z \phi^1, \partial_z \phi^2$ are solutions of equation (4.16). Assuming that they belong to $\mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$, by proposition 4.8, $\partial_z \phi^1 = \partial_z \phi^2$. Hence $\partial_\tau(\phi^1 - \phi^2) = 0$ which implies that $\phi^1(z, \tau) = \phi^2(z, \tau) + \tilde{\phi}(z)$ and thus, using that $\partial_z \phi^1 = \partial_z \phi^2$, we conclude that $\partial_z \tilde{\phi} = 0$.

For any $\xi \in \mathbb{C}$, we define

$$\phi_1(z, \tau) = \int_{+\infty}^0 \varphi(z + t, \tau) \, dt + \xi. \tag{4.33}$$

Obviously $\partial_z \phi_1 = \varphi$ and moreover the condition $\varphi \in \mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$ implies $\phi_1 - \xi \in \mathcal{X}_{\gamma, \rho_0, b}^{\ell}$. We note that, by remark 4.2, we have that $\sup_{(z, \tau) \in D_{\gamma, \rho_0} \times S_b} |z^{\ell+1} \partial_z \phi_1(z, \tau)| < +\infty$.

From the fact that φ are solutions of equation (4.16) and $\varphi \in \mathcal{X}_{\gamma, \rho_0, b}^{\ell+1}$, it is straightforward to check that ϕ_1 defined by formula (4.33) are solutions of equation (4.14) for any ξ. This ends the proof of theorem 3.1.

5. Distance between $\partial_z \phi^+$ and $\partial_z \phi^-$

Let $\gamma > 0$ and $0 < b < b_0$. We fix $\phi^\pm = \phi_0 + \mu \phi_1^\pm$ satisfying the conclusions of theorem 3.1.

In order to prove theorem 3.3 we define $\Delta\phi_1 = \phi_1^- - \phi_1^+$. This function has the following immediate properties which come from those of $\phi_1^{\pm}$.

(i) $\Delta\phi_1$ is 2π-periodic with respect to τ.
(ii) It is analytic on $E_{\gamma,\rho_0} \times S_b \times B(\mu_0)$. This is due to the fact that $E_{\gamma,\rho_0} \subset D_{\gamma,\rho_0}^- \cap D_{\gamma,\rho_0}^+$. We recall that $E_{\gamma,\rho}$ was defined in (3.1).
(iii) $\sup_{(z,\tau)\in E_{\gamma,\rho_0}\times S_b} |z^{\ell+1}\partial_z\Delta\phi_1| < +\infty$.

Since $\phi_1^{\pm}$ are necessarily solutions of equation (4.14), subtracting equation (4.14) for ϕ_1^- and ϕ_1^+, respectively, we obtain that $\Delta\phi_1$ satisfies a partial differential equation of the form

$$\partial_\tau\varphi + (1 + \mu G^\ell(z,\tau))\partial_z\varphi = 0, \tag{5.1}$$

where G^ℓ is an analytic function on $E_{\gamma,\rho_0} \times S_b$, 2π-periodic on τ, depending not on $\phi_1^{\pm}$ but on $\partial_z\phi_1^{\pm}$. Later on, in section 5.2, we will write it in a more detailed way.

Next let us assume that equation (5.1) has a solution φ_0 such that $\psi_0(z,\tau) = (\varphi_0(z,\tau), \tau)$ is injective in $E_{\gamma,\rho} \times S_b$ for $\rho \geqslant \rho_0$ big enough. We claim that any solution of equation (5.1) defined in $E_{\gamma,\rho} \times S_b$ can be written as $\varphi = \chi(\varphi_0)$ for some function χ (this is a well-known property of homogeneous linear partial differential equations). Indeed, we note that, since ψ_0 is invertible, $\partial_z\varphi_0 \circ \psi_0^{-1} \neq 0$ in $E_{\gamma,\rho}$; hence using that both φ and φ_0 are solutions of equation (5.1),

$$\partial_\tau(\varphi \circ \psi_0^{-1}) = \frac{1}{\partial_z\varphi_0 \circ \psi_0^{-1}}\left(-\partial_z\varphi \circ \psi_0^{-1} \cdot \partial_\tau\varphi_0 \circ \psi_0^{-1} + \partial_\tau\varphi \circ \psi_0^{-1} \cdot \partial_z\varphi_0 \circ \psi_0^{-1}\right) = 0.$$

Therefore, $\varphi \circ \psi_0^{-1}(\xi, \tau)$ does not depend on τ and this implies that there exists a function χ such that $\varphi \circ \psi_0^{-1}(\xi, \tau) = \chi(\xi)$ and the claim is proved evaluating this equality at $\xi = \varphi_0(z,\tau)$.

Section 5.4 is devoted to proving the existence and useful properties of such a solution φ_0 of equation (5.1). Specifically we will prove that there exists a solution of the form $\varphi_0(z,\tau) = z - \tau + \mu g(z,\tau)$, with g 2π-periodic with respect to τ and satisfying all the properties stated in theorem 3.3. We will also prove that $\lim_{\text{Im}z\to-\infty} \partial_z g(z,\tau) = 0$. Finally we will see that $(\varphi_0(z,\tau), \tau)$ is injective in E_{γ,ρ_1} with $\rho_1 \geqslant \rho_0$ big enough.

In section 5.5, using this fact and properties (i)–(iii) that $\Delta\phi_1$ satisfies, we will end the proof of theorem 3.3. We sketch below the process that we will follow.

On the one hand, since $\Delta\phi_1$ is a solution of equation (5.1) analytic in $E_{\gamma,\rho_1} \times S_b \times B(\mu_0)$ (property (ii)), there exists an analytic function χ such that $\Delta\phi_1(z,\tau) = \chi(z - \tau + \mu g(z,\tau))$. On the other hand, $\Delta\phi_1$ is 2π-periodic with respect to τ. This implies that χ_1 has to be a 2π-periodic function in such a way that $\Delta\phi_1$ has to be of the form

$$\Delta\phi_1(z,\tau) = \sum_{k\in\mathbb{Z}} \chi_k(\mu)e^{ik(z-\tau+\mu g(z,\tau))}.$$

(We notice that, χ_k are analytic functions in $B(\mu_0)$.) Finally, using that $\Delta\phi_1$ goes to 0 as $\text{Im}z \to -\infty$ (property (iii)), one can check that $\chi_k = 0$ for $k > 0$. Henceforth

$$\partial_z\Delta\phi_1(z,\tau) = \sum_{k<0} ik\chi_k(\mu)e^{ik(z-\tau+\mu g(z,\tau))}(1 + \mu\partial_z g(z,\tau)) \tag{5.2}$$

and since $\lim_{\text{Im}z\to-\infty} \partial_z g(z,\tau) = 0$, we obtain the asymptotic expression (3.5) of theorem 3.3 as a consequence of (5.2).

In order to obtain asymptotic expression (3.6) we need only to look for the independents of μ terms of the functions $\partial_z\phi_1^{\pm}$ and compute their difference.

The subsection below is devoted to introducing the notation we will use throughout this section.

5.1. Notation

As in section 4, we will denote by $\langle \cdot \rangle$ the mean with respect to τ. For any 2π-periodic function, h, we also introduce $\{h\} = h - \langle h \rangle$.

Now we introduce the Banach spaces we deal with during this section. These spaces will be analogous to the ones defined in section 4.1 for functions defined on the domain $E_{\gamma,\rho} \times S_b \times B(\mu_0)$ (we recall that $E_{\gamma,\rho}$ was defined in (3.1)). We observe that the function $\Delta\phi_1 = \phi_1^- - \phi_1^+$ is defined on such a complex domain.

For any $\gamma, \rho, b > 0$ and $\nu \in \mathbb{R}$, to shorten the notation, we will write

$$\overline{E}_{\gamma,\rho} = E_{\gamma,\rho} \times B(\mu_0), \qquad \mathcal{E}_{\gamma,\rho,b} = E_{\gamma,\rho} \times S_b \times B(\mu_0).$$

We define the spaces

$$Y^\nu = \{h : \overline{E}_{\gamma,\rho} \to \mathbb{C} : h \text{ is analytic and } \|h\|_\nu := \sup_{(z,\mu) \in \overline{E}_{\gamma,\rho}} |z^\nu h(z,\mu)| < +\infty\}$$

if $\nu \neq 0$ and

$$Y^0 = \{h : \overline{E}_{\gamma,\rho} \to \mathbb{C} : h \text{ is analytic and } \|h\|_0 := \sup_{(z,\mu) \in \overline{E}_{\gamma,\rho}} \frac{|h(z,\mu)|}{|\log|z||} < +\infty\}$$

for $\nu = 0$. It is clear that the functional spaces Y^ν equipped with the norm $\|\cdot\|_\nu$ are Banach spaces.

We also introduce the spaces of Fourier series

$$\mathcal{Y}_{\gamma,\rho,b}^\nu = \left\{ f : \mathcal{E}_{\gamma,\rho,b} \to \mathbb{C} : \text{analytic, } f(z,\tau,\mu) = \sum_{k \in \mathbb{Z}} f_k(z,\mu) e^{ik\tau}, \qquad f_k \in Y^\nu \right.$$

$$\left. \text{and } \|f\|_{\nu,b} := \sum_{k \in \mathbb{Z}} \|f_k\|_\nu e^{|k|b} < +\infty \right\} \tag{5.3}$$

The functional space $\mathcal{Y}_{\gamma,\rho,b}^\nu$ of Fourier series endowed with the norm $\|\cdot\|_{\nu,b}$ is a Banach space.

We also define the auxiliary Banach space

$$\overline{\mathcal{Y}}_{\gamma,\rho,b}^0 = \left\{ f : \mathcal{E}_{\gamma,\rho,b} \to \mathbb{C} : \text{analytic, } f(z,\tau,\mu) = \sum_{k \in \mathbb{Z}} f_k(z,\mu) e^{ik\tau} \right.$$

$$\left. \text{and } \|f\|_{\overline{0},b} := \sum_{k \in \mathbb{Z}} \sup_{(z,\mu) \in \overline{E}_{\gamma,\rho}} |f_k(z,\mu)| e^{|k|b} < +\infty \right\}.$$

For notational need we introduce $\overline{\mathcal{Y}}_{\gamma,\rho,b}^\nu = \mathcal{Y}_{\gamma,\rho,b}^\nu$ and $\|\cdot\|_{\overline{\nu},b} = \|\cdot\|_{\nu,b}$ if $\nu \neq 0$.

Remark 5.1. We note that $\mathcal{X}^{\nu,\pm} \subset \mathcal{Y}^\nu$ and $\mathcal{X}^{0,\pm} \subset \overline{\mathcal{Y}}^0$.

Let $\phi^\pm = \phi_0 + \phi_1^\pm$ satisfying the conclusions of theorem 3.1. We note that, by remark 4.2, $\partial_z \phi_1^\pm \in \mathcal{X}_{\gamma,\rho,b}^{\ell+1,\pm}$, respectively, for any $\gamma > 0$, $\rho \geqslant \rho_0$ and $0 < b < b_0$. Hence the function $\Delta\phi_1 = \phi_1^- - \phi_1^+$ satisfies that $\partial_z \Delta\phi_1$ belongs to $\mathcal{Y}_{\gamma,\rho,b}^{\ell+1}$.

We will denote $\mathcal{Y}_{\gamma,\rho,b}^\nu$ simply by $\mathcal{Y}^\nu$ (and $\overline{\mathcal{Y}}_{\gamma,\rho,b}^\nu$ by $\overline{\mathcal{Y}}^\nu$) so that there is no danger of confusion on the definition domain. We will also write $\|\cdot\|_{\mathcal{Y}_{\gamma,\rho,b}^\nu} = \|\cdot\|_{\nu,b}$ and $\|\cdot\|_{\overline{\mathcal{Y}}_{\gamma,\rho,b}^\nu} = \|\cdot\|_{\overline{\nu},b}$, when it is necessary to emphasize the complex domain where the functions are defined.

The Banach spaces $\overline{\mathcal{Y}}^\nu$ (and henceforth, $\mathcal{Y}^\nu$ for $\nu \neq 0$), satisfy the same properties as the ones given in section 4.1 for $\mathcal{X}^\nu$. Specifically we have the following lemma.

Lemma 5.2. *Let $\gamma, b, \rho > 0$ and $\nu, \eta \in \mathbb{R}$.*

(i) If $\eta \geqslant \nu$, then $\mathcal{Y}^\eta \subset \mathcal{Y}^\nu$ and $\overline{\mathcal{Y}}^\eta \subset \overline{\mathcal{Y}}^\nu$. Moreover we have that

$$\|h\|_{\overline{\nu},b} \leqslant \rho^{\nu-\eta}\|h\|_{\overline{\eta},b}, \qquad if \ h \in \overline{\mathcal{Y}}^\nu.$$

(ii) If $h \in \overline{\mathcal{Y}}^\nu$ and $g \in \overline{\mathcal{Y}}^\eta$, then the product $hg \in \overline{\mathcal{Y}}^{\nu+\eta}$ and

$$\|hg\|_{\overline{\nu+\eta},b} \leqslant \|h\|_{\overline{\nu},b}\|g\|_{\overline{\eta},b}.$$

(iii) If $h \in \overline{\mathcal{Y}}^\nu_{\gamma,\rho,b}$, then there exists a constant $A_{\gamma,\nu}$ such that for $l \in \mathbb{N}\backslash\{0\}$ we have that

$$\partial_z^l h \in \overline{\mathcal{Y}}^{l+\nu}_{2\gamma,2\rho,b} \qquad and \qquad \|\partial_z^l h\|_{\overline{l+\nu},b} \leqslant l!2^{-l}C_\gamma^{-l}A_{\gamma,\nu}\|h\|_{\overline{\mathcal{Y}}^\nu_{\gamma,\rho,b}},$$

where the constant C_γ was defined by property (4.8).

(iv) Assume that $\eta > -1$. We fix $F \in \overline{\mathcal{Y}}^\nu_{\gamma,\rho,b}$ and $f \in \overline{\mathcal{Y}}^\eta_{\gamma,\rho,b}$. Let ρ be such that

$$\mu_0 C_\gamma^{-1}\|f\|_{\overline{\mathcal{Y}}^\eta_{\gamma,\rho,b}} \leqslant \rho^{\eta+1}. \tag{5.4}$$

We define the formal expression

$$\mathcal{T}_F(f)(z,\tau) = \sum_{l \geqslant 1} \frac{1}{l!}\partial_z^l F(z,\tau)\mu^l f^l(z,\tau).$$

Then there exists a constant $B_{\gamma,\nu}$ such that

$$\mathcal{T}_F(f) \in \overline{\mathcal{Y}}^{\nu+\eta+1}_{2\gamma,2\rho,b}, \qquad \|\mathcal{T}_F(f)\|_{\overline{\nu+\eta+1},b} \leqslant \mu_0 B_{\gamma,\nu}\|F\|_{\overline{\mathcal{Y}}^\nu_{\gamma,\rho,b}}\|f\|_{\overline{\mathcal{Y}}^\eta_{\gamma,\rho,b}}.$$

Moreover, the function $\tilde{F}(z,\tau) = F(z + \mu f(z,\tau),\tau)$ belongs to $\overline{\mathcal{Y}}^\nu_{2\gamma,2\rho,b}$.

(v) Let $\eta > -1$, $F \in \mathcal{Y}^0_{\gamma,\rho,b}$ and $f \in \overline{\mathcal{Y}}^\eta_{\gamma,\rho,b}$ with F satisfying that $\partial_z F \in \mathcal{Y}^1_{\gamma,\rho,b}$. If ρ satisfies condition (5.4), then

$$\mathcal{T}_F(f) \in \mathcal{Y}^{\eta+1}_{2\gamma,2\rho,b}, \qquad \|\mathcal{T}_F(f)\|_{\eta+1,b} \leqslant \mu_0 B_{\gamma,0}\|\partial_z F\|_{\mathcal{Y}^1_{\gamma,\rho,b}}\|f\|_{\overline{\mathcal{Y}}^\eta_{\gamma,\rho,b}}.$$

Moreover $\tilde{F}(z,\tau) = F(z + \mu f(z,\tau),\tau)$ belongs to $\mathcal{Y}^0_{2\gamma,2\rho,b}$.

Proof. The proof of (i)–(iii) of lemma 5.2 is completely analogous to the proof of lemma 4.3. We only have to take into account two facts: the first is that if $z \in E_{\gamma,\rho}$, then $|z| \geqslant \rho$; the second we need is that

$$\{u \in \mathbb{C} : |u - z| < 2C_\gamma|z|\} \subset E_{\gamma,\rho}, \qquad z \in E_{2\gamma,2\rho}. \tag{5.5}$$

Item (iv) is proved as in lemma 4.3 by using property (5.5). To check (v) we apply (iii) to $\partial_z F$ and we proceed in a way completely analogous to the one in (iv) of lemma 4.3. ∎

5.2. The equation for $\phi_1^- - \phi_1^+$

Let $\gamma > 0$ and $0 < b < b_0$. According to theorem 3.1 there exist infinitely many solutions $\phi^\pm = \phi_0 + \mu\phi_1^\pm$ of the Hamilton–Jacobi equation (3.3) analytic on the domain $D^\pm_{\gamma,\rho_0} \times S_b$, 2π-periodic with respect to τ and such that $\partial_z\phi_1^\pm$ are the unique possible choices satisfying that

$$\sup_{(z,\tau)\in D^\pm_{\gamma,\rho_0}\times S_b} |z^{\ell+1}\partial_z\phi_1^\pm(z,\tau)| < +\infty.$$

We recall that $\rho_0 = \rho_0(\gamma, b, \ell, r)$ was given in theorem 3.1.

For any two of those solutions $\phi^\pm$ we denote $\Delta\phi_1 = \phi_1^- - \phi_1^+$ which is defined on $E_{\gamma,\rho_0} \times S_b \subset D^+_{\gamma,\rho_0} \cap D^-_{\gamma,\rho_0} \times S_b$. Since, $\phi_1^\pm$ are solutions of equation (4.14), subtracting equation (4.14) for both ϕ_1^- and ϕ_1^+, respectively, we get

$$\partial_\tau\Delta\phi_1 + \partial_z\Delta\phi_1 + \mathcal{H}_1(z, \partial_z\phi^-, \tau) - \mathcal{H}_1(z, \partial_z\phi^+, \tau) + \frac{\mu}{2}z^{2r}\left[(\partial_z\phi_1^-)^2 - (\partial_z\phi_1^+)^2\right] = 0.$$

Denoting

$$G^\ell(z, \tau) = \sum_{j=1}^{N} \mu^{j-1} Q_j(\tau) z^{2rj-\ell} \sum_{k=0}^{j-1} (\partial_z \phi_1^-)^k (\partial_z \phi_1^+)^{j-1-k} + \frac{1}{2} z^{2r} \left(\partial_z \phi_1^- + \partial_z \phi_1^+ \right), \tag{5.6}$$

it is straightforward to see that $\Delta \phi_1$ satisfies the equation

$$\partial_\tau \varphi + (1 + \mu G^\ell(z, \tau)) \partial_z \varphi = 0. \tag{5.7}$$

Lemma 5.3. *The function $G^\ell - Q_1 z^{-\ell+2r}$ belongs to $\mathcal{Y}^{\ell-2r+1}$ and it can be written in the form*

$$G^\ell(z, \tau) = Q_1(\tau) z^{-\ell+2r} + \frac{1}{2} z^{2r} (\partial_z \phi_1^- + \partial_z \phi_1^+)(1 + 2z^{-\ell+2r} \mu Q_2(\tau)) + \overline{G}^\ell(z, \tau) \tag{5.8}$$

with Q_1 having zero mean with respect to τ and $\overline{G}^\ell \in \mathcal{Y}^{3(\ell-2r)+2}$. Moreover

$$\langle G^\ell \rangle \in \begin{cases} \mathcal{Y}^2 & \text{if } \ell = 2r, \ Q_1 = 0 \text{ and } \langle F_0 \cdot Q_2 \rangle = 0, \\ \mathcal{Y}^{\ell-2r+1} & \text{otherwise,} \end{cases} \tag{5.9}$$

where F_0 is such that $\partial_\tau F_0 = Q_0$ and $\langle F_0 \rangle = 0$.

Proof. Formula (5.8) is straightforward from the definition of G^ℓ. Moreover, using that $\partial_z \phi_1^\pm \in \mathcal{X}^{\ell+1,\pm}$, we easily get that $\overline{G}^\ell \in \mathcal{Y}^{3(\ell-2r)+2}$.

Now we deal with the statement related to $\langle G^\ell \rangle$. We observe that $G^\ell - Q_1 z^{\ell-2r} \in \mathcal{Y}^{\ell-2r+1}$. Hence, since Q_1 has zero mean, in any case we have that $\langle G^\ell \rangle \in \mathcal{Y}^{\ell-2r+1}$. It only remains to check that if $\ell = 2r$, $Q_1 = 0$ and $\langle F_0 \cdot Q_2 \rangle = 0$, $\langle G^\ell \rangle \in \mathcal{Y}^2$. First we claim that, in this case,

$$\partial_z \phi_1^\pm - 2r \frac{F_0}{z^{2r+1}} \in \mathcal{Y}^{2r+2}. \tag{5.10}$$

Indeed, we deal with the + case, being the − case analogous. By proposition 4.8, $\partial_z \phi_1^+ - \mathcal{B}(\psi_1^{2r}) \in \mathcal{X}^{2r+2,+}$. Trivially,

$$\mathcal{B}(\psi_1^{2r}) = 2r \int_{+\infty}^{0} \frac{Q_0(\tau + t)}{(z + t)^{2r+1}} \, dt = 2r \frac{F_0(\tau)}{z^{2r+1}} + 2r(2r + 1) \mathcal{B}(F_0 z^{-2r-2})$$

and therefore, $\mathcal{B}(\psi_1^{2r}) - 2r F_0(\tau) z^{-2r-1} \in \mathcal{X}^{2r+2,+} \subset \mathcal{Y}^{2r+2}$ because F_0 has zero mean.

Looking at expression (5.8) of G^ℓ, and using property (5.10), we deduce that

$$G^\ell - 4r z^{-1} F_0 (1 + \mu Q_2) \in \mathcal{Y}^2$$

and henceforth, property (5.9) is proved provided that $\langle F_0 \rangle = \langle F_0 \cdot Q_2 \rangle = 0$. ∎

Remark 5.4. Since G^ℓ depends on $\partial_z \phi_1^\pm$, but not on $\phi_1^\pm$ themselves, it is independent of the choice of the solutions $\phi^\pm$.

As we pointed out at the beginning of this section, the next step in proving theorem 3.3 is to find a solution of the partial differential equation (5.7) of the form $\varphi_0(z, \tau) = z - \tau + \mu g(z, \tau)$. To obtain such a solution, we will need to solve explicitly the linear equation $\partial_\tau h + \partial_z h = \psi$ with $\psi \in \mathcal{Y}^\nu$ a known function. The next subsection is devoted to studying this equation.

5.3. An explicit solution of equation $\partial_\tau h + \partial_z h = \psi$ in $\mathcal{Y}^\nu_{\gamma,\rho,b}$

We fix $b, \rho, \gamma > 0$, $\nu \geqslant 0$ and $\psi \in \mathcal{Y}^\nu$. We denote by ψ_k the k-Fourier coefficient of ψ and we consider the operator $\mathcal{G}$ formally defined by

$$\mathcal{G}(\psi)(z, \tau) = \sum_{k \in \mathbb{Z}} (\mathcal{G}(\psi))_k(z) e^{ik\tau}, \tag{5.11}$$

where its Fourier coefficients are given by

$$(\mathcal{G}(\psi))_0(z) = \int_{-i\rho}^{z} \psi_0(t)\, dt \qquad \text{if } 0 \leqslant \nu \leqslant 1 \tag{5.12}$$

$$(\mathcal{G}(\psi))_0(z) = \int_{-i\infty}^{z} \psi_0(t)\, dt \qquad \text{if } \nu > 1 \tag{5.13}$$

$$(\mathcal{G}(\psi))_k(z) = \int_{-i\rho}^{z} e^{ik(t-z)} \psi_k(t)\, dt \qquad \text{if } k > 0 \tag{5.14}$$

$$(\mathcal{G}(\psi))_k(z) = \int_{-i\infty}^{z} e^{ik(t-z)} \psi_k(t)\, dt \qquad \text{if } k < 0. \tag{5.15}$$

The following lemma proves that, under suitable conditions, $\mathcal{G}(\psi)$ is well defined. This implies that $h = \mathcal{G}(\psi)$ is a solution of equation $\partial_\tau h + \partial_z h = \psi$.

Lemma 5.5. *Let $\gamma, b, \nu > 0$ and $\rho \geqslant \max\{2\nu, 1\}$. For any $\psi \in \mathcal{Y}^\nu_{\gamma,\rho,b}$ we have that*

(i) $\mathcal{G}(\psi) \in \mathcal{Y}^{\nu-1}_{\gamma,\rho,b}$ and $\partial_z \mathcal{G}(\psi) \in \mathcal{Y}^\nu_{\gamma,\rho,b}$. Moreover, there exists a constant $C_{\nu,\gamma}$ only depending on ν and γ such that,

$$\|\mathcal{G}(\psi)\|_{\nu-1,b} \leqslant C_{\nu,\gamma} \|\psi\|_{\nu,b} \quad \text{and} \quad \|\partial_z \mathcal{G}(\psi)\|_{\nu,b} \leqslant C_{\nu,\gamma} \|\psi\|_{\nu,b}. \tag{5.16}$$

(ii) If ψ has zero mean with respect to τ, then $\mathcal{G}(\psi) \in \mathcal{Y}^\nu_{\gamma,\rho,b}$, $\langle \mathcal{G}(\psi) \rangle = 0$ and

$$\|\mathcal{G}(\psi)\|_{\nu,b} \leqslant C_{\nu,\gamma} \|\psi\|_{\nu,b}.$$

Proof. We write $h = \mathcal{G}(\psi)$ and we denote by h_k its k-Fourier coefficient. To prove (i) and (ii) we have to bound h_k. We claim that for all $z \in E_{\gamma,\rho}$,

(a) If either $k < 0$ and $\nu > 0$, or $k = 0$ and $\nu > 1$,

$$|h_k(z)| \leqslant \|\psi_k\|_\nu \int_{-\infty}^{0} \frac{e^{-kt}}{(|z|^2 + t^2)^{\nu/2}}\, dt. \tag{5.17}$$

(b) Otherwise, denoting $c_\gamma = \gamma^{-1}(1 + \gamma^2)^{1/2}$,

$$|h_k(z)| \leqslant c_\gamma \|\psi_k\|_\nu \int_{0}^{|\text{Im}z+\rho|} \frac{e^{-kt}}{|t + \text{Im}z|^\nu}\, dt. \tag{5.18}$$

Indeed, in the case (a) h_k is defined by equation (5.15) and equation (5.13), respectively. The condition $\psi \in \mathcal{Y}^\nu_{\gamma,\rho,b}$ implies that $e^{iks}\psi_k(s)$ is analytic on $E_{\gamma,\rho}$ and $\lim_{\text{Im}s \to -\infty} e^{iks}s\psi_k(s) = 0$ (either if $k = 0$ and $\psi_0 \in \mathcal{Y}^\nu_{\gamma,\rho,b}$ with $\nu > 1$, or $k < 0$ and $\psi_k \in \mathcal{Y}^\nu_{\gamma,\rho,b}$ with $\nu > 0$). Thus, by Cauchy's theorem we can change the path of integration to $z + it$ and therefore

$$|h_k(z)| \leqslant \left| i \int_{-\infty}^{0} e^{-kt} \psi_k(z + it)\, dt \right| \leqslant \|\psi_k\|_\nu \int_{-\infty}^{0} \frac{e^{-kt}}{|z + it|^\nu}\, dt.$$

Finally, since $|z + it|^2 \geqslant |z|^2 + t^2$ if $t < 0$, we get bound (5.17). In the case (b), bounding the integrals in definitions (5.12) and (5.14),

$$|h_k(z)| \leqslant \frac{|z + i\rho|}{|\text{Im } z + \rho|} \|\psi_k\|_\nu \int_{0}^{|\text{Im } z+\rho|} \frac{e^{-kt}}{|t + \text{Im } z|^\nu}\, dt$$

and, since $|z + i\rho||\text{Im } z + \rho|^{-1} \leqslant c_\gamma$, (5.18) holds.

Now we claim that

$$\|h_k\|_\nu \leqslant 2c_\gamma^{\nu+1}|k|^{-1}\|\psi_k\|_\nu \qquad \text{for } k \neq 0. \tag{5.19}$$

Indeed, let $z \in E_{\gamma,\rho}$. First we deal with $k < 0$. Obviously, bound (5.17) implies that

$$|z^\nu h_k(z)| \leqslant \|\psi_k\|_\nu \int_{-\infty}^0 e^{-kt}\,dt = |k|^{-1}\|\psi_k\|_\nu \leqslant 2c_\gamma^{\nu+1}|k|^{-1}\|\psi_k\|_\nu$$

provided that $c_\gamma > 1$. If $k > 0$ we define $I_\nu = \int_0^{|\operatorname{Im} z+\rho|} e^{-kt}|t + \operatorname{Im} z|^{-\nu}\,dt$. Integrating by parts I_ν, it is easily checked that $I_\nu \leqslant k^{-1}\left(|\operatorname{Im} z|^{-\nu} + \nu\rho^{-1}I_\nu\right)$. Thus, since $\rho \geqslant 2\nu$, we obtain bound (5.19) from (5.18) by using the fact that $|z| \leqslant c_\gamma|\operatorname{Im} z|$.

We prove (i). Let $\nu > 0$. We define the constants $B_{\nu,\gamma} = (1-\nu)^{-1}c_\gamma$ if $\nu < 1$, $B_{1,\gamma} = c_\gamma$ and $B_{\nu,\gamma} = \int_0^{+\infty}(1+s^2)^{-\nu/2}\,ds$ if $\nu > 1$. With this notation

$$\|h_0\|_{\nu-1} \leqslant B_{\nu,\gamma}\|\psi_0\|_\nu. \tag{5.20}$$

Proving bound (5.20) is straightforward by computing the integrals in formulae (5.17) and (5.18) in the corresponding cases. We take $C_{\nu,\gamma} = \max\{1 + 2c_\gamma^{\nu+1}, B_{\nu,\gamma}\}$ and we notice that bounds (5.20), (5.19) and (i) of lemma 4.3 imply

$$\|h\|_{\nu-1,b} = \|h_0\|_{\nu-1} + \sum_{k\in\mathbb{Z}\setminus\{0\}}\|h_k\|_{\nu-1}e^{|k|b}$$

$$\leqslant B_{\nu,\gamma}\|\psi_0\|_\nu + 2c_\gamma^{\nu+1}\rho^{-1}\sum_{k\in\mathbb{Z}\setminus\{0\}}\|\psi_k\|_\nu e^{|k|b} \leqslant C_{\nu,\gamma}\|\psi\|_{\nu,b}$$

provided that $\rho \geqslant 1$. In this way we get the first bound in property (5.16).

Next we prove the second bound in property (5.16). Taking derivatives in formulae (5.12)–(5.15),

$$\partial_z h_k = -\mathrm{i}kh_k + \psi_k, \qquad \text{for all } k \in \mathbb{Z}. \tag{5.21}$$

Hence we have that $\partial_z h_0 = \psi_0$ and, from bound (5.19), $\|\partial_z h_k\|_\nu \leqslant (1 + 2c_\gamma^{\nu+1})\|\psi_k\|_\nu$ for $k \neq 0$. From the Fourier series of $\partial_z h$ and the definition of the norm $\|\cdot\|_{\nu,b}$, we get $\|\partial_z h\|_{\nu,b} \leqslant C_{\nu,\gamma}\|\psi\|_{\nu,b}$.

Finally, we prove (ii). Let $\nu > 0$. We observe that, $\langle\psi\rangle = 0$ implies $h_0 = 0$. Thus (ii) follows from property (5.19). ∎

Remark 5.6. By using equality (5.21) one checks that $\mathcal{G}(\psi)$ is a solution of equation $\partial_\tau h + \partial_z h = \psi$.

5.4. A solution φ_0 of equation (5.7) of the form $\varphi_0(z,\tau) = z - \tau + \mu g(z,\tau)$

Our goal in this subsection is to prove the following result.

Proposition 5.7. *Let $\gamma > 0$ and $0 < b < b_0$. There exists $\rho_1 = \rho_1(\gamma, b, \ell, r)$ such that the equation (5.7)*

$$\partial_\tau\varphi + \partial_z\varphi(1 + \mu G^\ell) = 0 \tag{5.22}$$

has a solution φ_0 of the form $\varphi_0(z,\tau) = z - \tau + \mu g(z,\tau)$ with g satisfying that $g \in \mathcal{Y}_{\gamma,\rho_1,b}^{\ell-2r}$ and $\partial_z g \in \mathcal{Y}_{\gamma,\rho_1,b}^{\ell-2r+1}$.

In the special case that $\ell = 2r$, $Q_1 = 0$ and $\langle F_0 \cdot Q_2\rangle = 0$, then $g \in \mathcal{Y}_{\gamma,\rho_1,b}^1$ and $\partial_z g \in \mathcal{Y}_{\gamma,\rho_1,b}^2$.

Moreover, $\psi_0(z,\tau) = (\varphi_0(z,\tau),\tau)$ defines an injective map on E_{γ,ρ_1}.

A function φ_0 is a solution of equation (5.22) of the form $\varphi_0(z, \tau) = z - \tau + \mu g(z, \tau)$ if and only if g is a solution of the equation

$$\partial_\tau g + \partial_z g(1 + \mu G^\ell) = -G^\ell. \tag{5.23}$$

To check that equation (5.23) has solutions satisfying the conclusions of proposition 5.7 we state a technical lemma which will be proved later.

Lemma 5.8. *We fix $\gamma, b, \rho > 0$. Let $H \in \mathcal{Y}_{\gamma/2,\rho,b}^\eta$ be such that $\mathcal{G}(H) \in \mathcal{Y}_{\gamma/2,\rho,b}^\nu$ for some $\eta > 0$ and $\nu \geqslant 0$.*

If either $\nu > 0$, or $\nu = 0$ and $\eta \geqslant 1$, there exists $\rho_2 = \rho_2(\gamma, b, \nu, \eta, \rho)$ such that the equation

$$\partial_\tau h + \partial_z h(1 + \mu H) = -H \tag{5.24}$$

has a solution $h \in \mathcal{Y}_{\gamma,\rho_2,b}^\nu$ satisfying that $\partial_z h \in \mathcal{Y}_{\gamma,\rho_2,b}^{\nu+1}$.

To prove proposition 5.7 from lemma 5.8 we have to check that in each case G^ℓ satisfies the hypotheses of this lemma.

Proof of proposition 5.7. We fix $\gamma > 0$ and $0 < b < b_0$. We are forced to distinguish the following three cases.

- Case $\ell > 2r$. By lemma 5.3, $G^\ell = Q_1 z^{-\ell-2r} + \tilde{G}^\ell$ with $\tilde{G}^\ell \in \mathcal{Y}_{\gamma,\rho_0,b}^{\ell-2r+1}$. Therefore $G^\ell \in \mathcal{Y}_{\gamma,\rho_0,b}^{\ell-2r}$. Moreover, since Q_1 has zero mean with respect to τ, by lemma 5.5, $\mathcal{G}(G^\ell) \in \mathcal{Y}_{\gamma,\rho_0,b}^{\ell-2r}$ and lemma 5.8 can be applied in this case with $H = G^\ell$ and $\nu = \eta = \ell - 2r > 0$.
- Case $\ell = 2r$, $Q_1 = 0$ and $\langle F_0 \cdot Q_2 \rangle = 0$. Again using lemma 5.3 one deduce that $G^\ell = \langle G^\ell \rangle + \{G^\ell\}$ with $\langle G^\ell \rangle \in \mathcal{Y}_{\gamma,\rho_0,b}^2$ and $\{G^\ell\} \in \mathcal{Y}_{\gamma,\rho_0,b}^1$ having zero mean with respect to τ. Using similar arguments as in the previous case, we conclude that we can apply lemma 5.8 with $H = G^\ell$ and $\nu = \eta = 1$.
- Case $\ell = 2r$ but either $Q_1 \neq 0$ or $\langle F_0 \cdot Q_2 \rangle \neq 0$. The change of coordinates

$$z = u + \mu F_1(\tau), \qquad \tilde{g}(u, \tau) = g(u + \mu F_1(\tau), \tau)$$

transforms equation (5.23) into

$$\partial_\tau \tilde{g} + \partial_u \tilde{g}(1 + \mu \tilde{G}^\ell) = -Q_1 - \tilde{G}^\ell$$

with $\tilde{G}^\ell(u, \tau) = G^\ell(u + \mu F_1(\tau), \tau) - Q_1(\tau)$. We note that, by lemma 5.3, $G^\ell - Q_1 \in \mathcal{Y}_{\gamma/8,\tilde{\rho}_0/8,b}^1$, with $\tilde{\rho}_0 = \max\{8\rho_0, 8\mu_0 C_{\gamma/8}^{-1} \|F_1\|_{0,b}\}$. Therefore, by (iv) of lemma 5.2, $\tilde{G}^\ell \in \mathcal{Y}_{\gamma/4,\tilde{\rho}_0/4,b}^1$. We take $\tilde{g} = -F_1 + \overline{g}$ and we notice that $\overline{g}$ has to satisfy the equation

$$\partial_\tau \overline{g} + \partial_u \overline{g}(1 + \mu \tilde{G}^\ell) = -\tilde{G}^\ell. \tag{5.25}$$

This equation is under the hypotheses of lemma 5.8. Indeed, we have already seen that $\tilde{G}^\ell \in \mathcal{Y}_{\gamma/4,\tilde{\rho}_0/4,b}^1$. Moreover by lemma 5.5, $\mathcal{G}(\tilde{G}^\ell) \in \mathcal{Y}_{\gamma/4,\tilde{\rho}_0/4,b}^0$. Hence lemma 5.8 works in this case with $H = \tilde{G}^\ell$, $\eta = 1$ and $\nu = 0$.

Let $\overline{g}$ be the solution of equation (5.25) given by lemma 5.8. We have that $\overline{g} \in \mathcal{Y}_{\gamma/2,\rho_2,b}^0$ and $\partial_u \overline{g} \in \mathcal{Y}_{\gamma/2,\rho_2,b}^1$. Going back to the original variables (z, τ), it is clear that

$$g(z, \tau) = -F_1(\tau) + \overline{g}(z - \mu F_1(\tau), \tau)$$

is a solution of equation (5.23). Moreover, since by lemma 5.8 $\overline{g} \in \mathcal{Y}_{\gamma/2,\rho_2,b}^0$ and $\partial_u \overline{g} \in \mathcal{Y}_{\gamma/2,\rho_2,b}^1$, applying (v) from lemma 5.2, we have that $g \in \mathcal{Y}_{\gamma,\tilde{\rho}_1,b}^0$ with $\tilde{\rho}_1 = \max\{2\rho_2, 2\mu_0 C_{\gamma/2}^{-1} \|F_1\|_{0,b}\}$. We also have that $\partial_z g \in \mathcal{Y}_{\gamma,\tilde{\rho}_1,b}^1$. This is due to the fact that $\partial_z g(z, \tau) = \partial_u \overline{g}(u - \mu F_1(\tau), \tau)$ and hence we are allowed to apply (iv) of lemma 5.2 to $\partial_u \overline{g} \in \mathcal{Y}_{\gamma/2,\rho_2,b}^1 \subset \mathcal{Y}_{\gamma/2,\tilde{\rho}_1/2,b}^1$.

We have proved that equation (5.22) has a solution φ_0 of the form $\varphi_0(z, \tau) = z - \tau + \mu g(z, \tau)$ with g satisfying at least that $g \in \mathcal{Y}^0_{\gamma, \tilde{\rho}_1, b}$ and $\partial_z g \in \mathcal{Y}^1_{\gamma, \tilde{\rho}_1, b}$. Now we check that $\psi_0(z, \tau) = (\varphi_0(z, \tau), \tau)$ is injective in $E_{\gamma, \rho_1} \times S_b$ if ρ_1 is big enough. Indeed, let $(z_1, \tau_1), (z_2, \tau_2) \in E_{\gamma, \rho} \times S_b$ be such that $\psi_0(z_1, \tau_1) = \psi_0(z_2, \tau_2)$. Clearly $\tau_1 = \tau_2$. Assume that $z_1 \neq z_2$. Then by the mean's value theorem,

$$|z_1 - z_2| \leqslant |\mu| \|\partial_z g\|_{1,b} |z_1 - z_2| \rho_1^{-1} < |z_1 - z_2|$$

if $\rho_1 \geqslant \max\{\tilde{\rho}_1, 2\mu_0 \|\partial_z g\|_{1,b}\}$, which is a contradiction. ∎

5.4.1. Proof of lemma 5.8. To prove lemma 5.8 we will find an explicit solution of equation (5.24) by means of a suitable linear operator.

We fix $\gamma, b, \rho > 0$ and ν, η, H satisfying the hypotheses of lemma 5.8 and we define the linear operator

$$\mathcal{F}(f) = -\partial_z \mathcal{G}(\mu H \cdot f). \tag{5.26}$$

Lemma 5.9. *There exists $\rho_2 = \rho_2(\gamma, b, \nu, \eta, \rho) \geqslant 2\rho$ such that the operator $(\mathrm{Id} - \mathcal{F})$ is invertible in $\mathcal{Y}^{\nu+1}_{\gamma, \rho_2, b}$.*

Proof. Let $\rho_2 = \max\{2\rho, \big(2\mu_0 C_{\nu+1,\gamma} \|H\|_{\mathcal{Y}^\eta_{\gamma, \rho, b}}\big)^{1/\eta}\}$ where $C_{\nu+1,\gamma}$ is the constant defined in lemma 5.5. We denote $\mathcal{Y}^l_{\gamma, \rho_2, b}$ and $\|\cdot\|_{\mathcal{Y}^l_{\gamma, \rho_2, b}}$ simply by $\mathcal{Y}^l$ and $\|\cdot\|_{l,b}$, respectively.

Since $\mathcal{F}$ is a linear map we only need to check that $\|\mathcal{F}\|_{\nu+1,b} < 1$. Let $f \in \mathcal{Y}^{\nu+1}$. We have that $H \in \mathcal{Y}^\eta_{\gamma, \rho, b} \subset \mathcal{Y}^\eta$, hence by (ii) of lemma 5.2, we deduce that $H \cdot f \in \mathcal{Y}^{\nu+\eta+1} \subset \mathcal{Y}^{\nu+1}$ provided $\eta > 0$. Moreover, $\|H \cdot f\|_{\nu+1,b} \leqslant \rho_2^{-\eta} \|H\|_{\eta,b} \|f\|_{\nu+1,b}$. Therefore, by lemma 5.5 and using definition (5.26) of $\mathcal{F}$, we have that

$$\|\mathcal{F}(f)\|_{\nu+1,b} \leqslant \mu_0 C_{\nu+1,2\gamma} \|H \cdot f\|_{\nu+1,b} \leqslant \mu_0 C_{\nu+1,2\gamma} \rho_2^{-\eta} \|H\|_{\eta,b} \|f\|_{\nu+1,b} < \tfrac{1}{2} \|f\|_{\nu+1,b}$$

provided that $\|H\|_{\eta,b} \leqslant \|H\|_{\mathcal{Y}^\eta_{\gamma, \rho, b}}$ and $\rho_2^\eta \geqslant 2\mu_0 C_{\nu+1,\gamma} \|H\|_{\mathcal{Y}^\eta_{\gamma, \rho, b}}$. ∎

We claim that if either $\nu > 0$ or, $\nu = 0$ and $\eta \geqslant 1$,

$$\partial_z \mathcal{G}(H) \in \mathcal{Y}^{\nu+1}_{\gamma, \rho_2, b} \tag{5.27}$$

with ρ_2 defined in lemma 5.9. Indeed, first we deal with the case $\nu > 0$. By hypothesis $\mathcal{G}(H) \in \mathcal{Y}^\nu_{\gamma/2, \rho, b}$, therefore using (iii) of lemma 5.2, $\partial_z \mathcal{G}(H) \in \mathcal{Y}^{\nu+1}_{\gamma, 2\rho, b} \subset \mathcal{Y}^{\nu+1}_{\gamma, \rho_2, b}$ provided that $\nu > 0$. In the case $\nu = 0$ and $\eta \geqslant 1$, we recall that $H \in \mathcal{Y}^\eta_{\gamma/2, \rho, b}$. Thus, using lemma 5.5 we conclude that $\partial_z \mathcal{G}(H) \in \mathcal{Y}^\eta_{\gamma/2, \rho, b}$. The claim is proved in this case taking into account that $\eta \geqslant 1$.

Now we define the functions

$$\overline{h} = \big(\mathrm{Id} - \mathcal{F}\big)^{-1} (-\partial_z \mathcal{G}(H))$$

and

$$h = -\mathcal{G}(H) - \mathcal{G}(\mu H \cdot \overline{h}). \tag{5.28}$$

We notice that, by (5.27) and lemma 5.9, $\overline{h} \in \mathcal{Y}^{\nu+1}_{\gamma, \rho_2, b}$.

It only remains to check that h so constructed is a solution of equation (5.24). First we note that, since $\mathcal{F}(\overline{h}) = \overline{h} + \partial_z \mathcal{G}(H)$, we have that

$$\partial_z h = -\partial_z \mathcal{G}(H) - \partial_z \mathcal{G}(\mu H \cdot \overline{h}) = -\partial_z \mathcal{G}(H) + \mathcal{F}(\overline{h}) = \overline{h}.$$

Therefore $\partial_z h \in \mathcal{Y}^{\nu+1}_{\gamma, \rho_2, b}$. Moreover, substituting $\overline{h}$ by $\partial_z h$ in equation (5.28) we obtain that

$$h = -\mathcal{G}(H) - \mathcal{G}(\mu H \cdot \partial_z h).$$

Consequently h is a solution of equation (5.24). Finally, using that $H \in \mathcal{Y}_{\gamma/2,\rho,b}^{\eta}$, that $\mathcal{G}(H) \in \mathcal{Y}_{\gamma/2,\rho,b}^{\nu}$ and lemma 5.5, we conclude that $h \in \mathcal{Y}_{\gamma/2,\rho,b}^{\nu} \cap \mathcal{Y}_{\gamma,\rho_2,b}^{\nu+\eta} \subset \mathcal{Y}_{\gamma,\rho_2,b}^{\nu}$ and the lemma is proved.

5.5. End of the proof of theorem 3.3

We fix $\gamma > 0, 0 < b < b_0$. We write $\varphi_0(z,\tau) = z - \tau + \mu g(z,\tau)$ where g is the function that satisfies the conclusions of proposition 5.7. As we claimed in the previous subsection this implies that φ_0 is a solution of equation (5.7). Moreover $\psi_0(z,\tau) = (\varphi_0(z,\tau),\tau)$ is injective on E_{γ,ρ_1} where ρ_1 is given by proposition 5.7.

Therefore as we pointed out at the beginning of this section, any solution of equation (5.7) can be expressed as a function of φ_0. In particular, there exists an analytic function χ such that

$$\Delta\phi_1 = \chi(\varphi_0).$$

5.5.1. Proof of the asymptotic expression (3.5) of theorem 3.3.

We claim that $\partial_\zeta \chi(\zeta)$ goes to 0 as $\operatorname{Im}\zeta \to -\infty$. Indeed, we notice that, if $z \in E_{\gamma,\rho_1}$ with $|\operatorname{Im}z|$ big enough, $|\operatorname{Re}z| < -\gamma^{-1}\operatorname{Im}z$ and $|\operatorname{Im}\tau| < b \leqslant -\operatorname{Im}z/3$. Then, since $g \in \mathcal{Y}_{\gamma,\rho_1,b}^{\ell-2r}$, we have that $|\operatorname{Im}\mu g(z,\tau)| \leqslant -\operatorname{Im}z/3$, if $|\operatorname{Im}z|$ is big enough, and thus

$$5\operatorname{Im}z/3 \leqslant \operatorname{Im}(z - \tau + \mu g(z,\tau)) \leqslant \operatorname{Im}z/3.$$

Moreover, from the fact that $\partial_z\Delta\phi_1(z,\tau)$ goes to 0 as $\operatorname{Im}z \to -\infty$:

$$\lim_{\operatorname{Im}\zeta\to-\infty} \partial_\zeta\chi(\zeta) = \lim_{\operatorname{Im}z\to-\infty} \partial_\zeta\chi(z - \tau + \mu g(z,\tau))$$

$$= \lim_{\operatorname{Im}z\to-\infty} \partial_z\Delta\phi_1(z,\tau)(1 + \mu\partial_z g(z,\tau))^{-1} = 0. \qquad (5.29)$$

In the last equality we have used that $\partial_z g \in \mathcal{Y}_{\gamma,\rho_1,b}^{\ell-2r+1}$ and that $\Delta\phi_1 = \chi(\varphi_0)$.

On the other hand, since $\Delta\phi_1$ and g are 2π-periodic with respect to τ,

$$\chi(z - \tau + \mu g(z,\tau)) = \chi(z - \tau - 2\pi + \mu g(z,\tau + 2\pi)) = \chi(z - \tau - 2\pi + \mu g(z,\tau))$$

which implies that χ is 2π-periodic. Hence, $\partial_\zeta\chi$ can be expressed as a Fourier series of the form

$$\partial_\zeta\chi(\zeta) = \sum_{k\in\mathbb{Z}} ik\chi_k(\mu)e^{ik\zeta} \qquad (5.30)$$

where $\{\chi_k\}_{k\in\mathbb{Z}}$ are analytic functions in $B(\mu_0)$.

Finally the property $\partial_\zeta\chi(\zeta) \to 0$ as $\operatorname{Im}\zeta \to -\infty$ implies that $\chi_k(\mu)e^{ik\zeta}$ goes to 0 as $\operatorname{Im}\zeta \to -\infty$ and hence $\chi_k(\mu) = 0$ for $k > 0$. Then, since $\partial_z g \in \mathcal{Y}_{\gamma,\rho_1,b}^{1}$ at least, we have that

$$\partial_z\Delta\phi_1(z,\tau) = \sum_{k<0} ik\chi_k(\mu)e^{ik(z-\tau+\mu g(z,\tau))}(1 + \mu\partial_z g(z,\tau))$$

$$\sim -i\chi_{-1}(\mu)e^{-i(z-\tau+\mu g(z,\tau))} \qquad \text{as } \operatorname{Im}z \to -\infty. \qquad (5.31)$$

This gives asymptotic expression (3.5) taking $C(\mu) = \chi_{-1}(\mu)$.

5.5.2. The asymptotic expression (3.6) for $C(0)$.

Since $\partial_z\phi_1^{\pm}$ satisfy equation (4.16) we have that

$$\left[\partial_\tau(\partial_z\phi_1^{\pm}) - \partial_z(\partial_z\phi_1^{\pm})\right](z,\tau) = \ell Q_0(\tau)z^{-\ell-1} + O(\mu)$$

and therefore, from the fact that $\partial_z \phi_1^\pm$ are the unique solutions of (4.16) belonging to $\mathcal{X}_{\gamma,\rho_1,b}^{\ell+1,\pm}$, respectively, we obtain that

$$\partial_z(\phi_1^- - \phi_1^+)(z,\tau) = \ell \int_{-\infty}^{+\infty} \frac{Q_0(\tau+t)}{(z+t)^{\ell+1}}\, dt + O(\mu).$$

Finally formula (3.6) follows from the asymptotic expression (5.31) and the fact that $\partial_z(\phi^- - \phi^+) = \mu \partial_z(\phi_1^- - \phi_1^+)$.

6. Proof of corollary 3.5

First we state a technical lemma.

Lemma 6.1. *Let $k \in \mathbb{Z}^+\backslash\{0\}$. For any $\gamma > 0$, ρ big enough and $z \in E_{\gamma,\rho}$,*

$$\int_{-\infty}^{+\infty} \frac{e^{ikt}}{(z+t)^{\ell+1}}\, dt = i^{\ell+1} |k|^\ell \frac{2\pi}{\Gamma(\ell+1)} e^{-ikz}(1 + O(|\mathrm{Im}z|^{-1})), \qquad (6.1)$$

where Γ is the Gamma function.

Moreover, if $k < 0$,

$$\left| \int_{-\infty}^{+\infty} \frac{e^{ikt}}{(z+t)^{\ell+1}}\, dt \right| \leqslant 2K_{\ell+1,\gamma} e^{-2|k||\mathrm{Im}\,z|} \frac{1}{|z|^\ell} \qquad for\ z \in E_{\gamma,\rho}$$

where $K_{\ell+1,\gamma}$ is the constant defined in lemma 4.6.

Now we prove corollary 3.5. Substituting the definitions of a^k in expression (3.6) and using the asymptotic expressions of the integrals in lemma 6.1 we get

$$-iC(0)e^{-i(z-\tau)} \sim \ell i^{\ell+1} \frac{2\pi}{\Gamma(\ell+1)} \sum_{k>0} a^k |k|^\ell e^{-ik(z-\tau)}(1 + O(|\mathrm{Im}\,z|^{-1})) \qquad \text{as Im } z \to -\infty.$$

Therefore, since $a^1 \neq 0$,

$$C(0) = -i^\ell \frac{2\pi\ell}{\Gamma(\ell+1)} a^1 \neq 0. \qquad (6.2)$$

Finally (i) from corollary 3.5 follows from the asymptotic expression (3.5), (6.2) and the fact that g goes to 0 as Im $z \to -\infty$ and (ii) is proved from equations (3.5) and (6.2).

Proof of lemma 6.1. Let $z \in E_{\gamma,\rho}$. First we deal with $k < 0$. By Cauchy's theorem we can move the path of integration obtaining

$$\int_{-\infty}^{+\infty} \frac{e^{ikt}}{(z+t)^{\ell+1}}\, dt = e^{-2k\mathrm{Im}z} \int_{-\infty}^{+\infty} \frac{e^{ikt}}{(z+t+2i\mathrm{Im}z)^{\ell+1}}\, dt. \qquad (6.3)$$

Let $\tilde{z} = z + 2i\mathrm{Im}z$. We note that $\tilde{z}, -\tilde{z} \in D_{\gamma,\rho}^+ \cap D_{\gamma,\rho}^-$ and $|\tilde{z}| \geqslant |z|$. Using bound (4.24) in formula (6.3) we get the result.

Now we deal with $k > 0$. Performing trivial changes of variables we have that

$$\int_{-\infty}^{+\infty} \frac{e^{ikt}}{(z+t)^{\ell+1}}\, dt = \frac{e^{-ik\mathrm{Re}\,z}}{|\mathrm{Im}z|^\ell} \int_{-\infty}^{+\infty} \frac{e^{ikt|\mathrm{Im}z|}}{(t-i)^{\ell+1}}\, dt. \qquad (6.4)$$

In [3, p 80, formula (6.28)], the following expression is given:

$$\int_{-\infty}^{+\infty} \frac{e^{ikt/\varepsilon}}{(t-ic)^{\ell+1}}\, dt = i^{\ell+1} \left(\frac{k}{\varepsilon}\right)^\ell \frac{2\pi}{\Gamma(\ell+1)} e^{-kc/\varepsilon}(1 + O(\varepsilon)) \qquad (6.5)$$

with $\varepsilon > 0$, $c > 0$ and $k > 0$. Putting $\varepsilon = |\mathrm{Im}z|^{-1}$ and $c = 1$ in expression (6.5) we get formula (6.1) from expression (6.4).

We point out that, if $\ell \in \mathbb{N}$, the asymptotic expressions of this lemma can be easily obtained by using residues theory. ∎

Appendix

In this study, we have restricted ourselves to the case in which our initial Hamiltonian $\mathcal{H} = \mathcal{H}_0 + \mu\mathcal{H}_1$ is analytic with respect to τ, but this hypothesis is, in fact, not necessary. The purpose of this appendix is to justify that our proofs are also valid in a more general setting: the differentiable case with respect to τ.

First we present the precise statement of the results which ensures that, with the obvious changes, theorems 3.1 and 3.3 and corollary 3.5 are also valid in the differentiable case.

Theorem 6.2. *Consider the Hamiltonian system $\mathcal{H} = \mathcal{H}_0 + \mu\mathcal{H}_1$ with*

$$\mathcal{H}_0(z,w) = \frac{1}{2}w^2 z^{2r} - \frac{1}{2z^{2r}}, \qquad \mathcal{H}_1(z,w,\tau) = \frac{1}{z^\ell}\sum_{j=0}^{N} A_j(\tau,\mu)z^{2rj}w^j$$

where $r \geqslant 1$, $\ell \in \mathbb{R}$, $N \in \mathbb{N}$ and $\{A_j\}_{j \in \{0,\cdots,N\}}$ are arbitrary 2π-periodic functions with respect to τ, analytic with respect to μ in $B(\mu_0)$, for some $\mu_0 > 0$, C^q with respect to τ and such that the Fourier series of A_j is uniformly convergent for all $j \in \{0,\cdots,N\}$.

Then, if $\ell \geqslant 2r$, for all $\gamma > 0$ there exists $\rho_0 = \rho_0(\gamma,q,\ell,r) > 0$ such that the Hamilton–Jacobi equation associated with $\mathcal{H}$ has solutions $\phi^\pm : \mathcal{D}^\pm_{\gamma,\rho_0,b} \to \mathbb{C}$ of the form $\phi^\pm = \phi_0 + \mu\phi_1^\pm$, C^{q+1} and 2π-periodic with respect to τ, and analytic with respect to (z,μ). Moreover $\partial_z \phi_1^\pm$ is determined by the condition

$$\sup_{(z,\tau,\mu)\in\mathcal{D}^\pm_{\gamma,\rho_0,b}} |z^{\ell+1}\partial_z\phi_1^\pm(z,\tau,\mu)| < +\infty.$$

Theorem 3.3 and corollary 3.5 are also true in this new setting taking into account the new regularity of g with respect to τ, that is, g is C^q, analytic with respect to $(z,\mu) \in E_{\gamma,\rho} \times B(\mu_0)$ and such that the Fourier series of g is uniformly convergent.

To justify this result we take advantage of the fact that our results are valid for spaces of Fourier series satisfying the properties given in section 4.1 (and consequently in section 5.1).

The appropriate Banach spaces in this case are defined as follows. Let $\gamma, \rho > 0$ and $\nu \in \mathbb{R}$. We define the space $\mathcal{Z}^{\nu,\pm}_{\gamma,\rho}$ of Fourier series $f(z,\tau,\mu) = \sum_{k\in\mathbb{Z}} f_k(z,\mu)e^{ik\tau}$, with $f_k \in X^\nu_\pm$ analytic with respect to $(z,\tau) \in D^\pm_{\gamma,\rho} \times B(\mu_0)$, C^0 and such that the Fourier series of f is uniformly convergent. We endow $\mathcal{Z}^{\nu,\pm}_{\gamma,\rho}$ with the norm

$$\|f\|_{\nu,0} = \sum_{k\in\mathbb{Z}} \|f_k\|_\nu$$

and it becomes a Banach space. This fact can be proved as in [23].

It is straightforward to check that the Banach spaces $\mathcal{Z}^{\nu,\pm}_{\gamma,\rho}$ satisfy the properties given in lemma 4.3 and lemma 4.4. (We only need to take $b = 0$ and replace analyticity with respect to τ by continuity.)

Without any change in the procedure given in section 4 we can check that there exists a solution, $\varphi^+ \in \mathcal{Z}^{\ell+1,+}_{\gamma,\rho}$ of the fixed point equation $\varphi^+ = \mathcal{B}(\psi_1^\ell + \partial_z\psi_2^\ell(\varphi^+))$ and hence φ^+ is C^1 with respect to τ since $\partial_\tau\varphi^+ = \psi_1^\ell + \partial_z\psi_2^\ell(\varphi^+) - \partial_z(\mathcal{B}(\psi_1^\ell + \partial_z\psi_2^\ell(\varphi^+)))$. If either $\ell > 2r$, or $\ell = 2r$ with $Q_1 = 0$ and $\langle F_0 \cdot Q_2 \rangle = 0$, we have that $\partial_z\phi_1^+ = \varphi^+$ and therefore $\partial_z\phi_1^+$ is differentiable with respect to τ. Moreover, using definition (4.33) of ϕ_1^+ we conclude that ϕ_1^+ is differentiable with respect to τ, differentiating under the integral sign. In the special case $\ell = 2r$ and either $Q_1 \neq 0$ or $\langle F_0 \cdot Q_2 \rangle \neq 0$, we have that $\partial_z\phi_1^+(z,\tau) = \varphi^+(z - \mu F_1(\tau),\tau)$. Hence φ^+ is C^1 with respect to τ and henceforth, we have the same property for $\partial_z\phi_1^+$ and ϕ_1^+. We deal with the $-$ case in an analogous way.

Therefore we conclude that there exist solutions $\phi^\pm = \phi_0 + \mu\phi_1^\pm$ of the Hamilton–Jacobi equation $\partial_\tau \phi^\pm + \mathcal{H}(z, \partial_z \phi^\pm, \tau)$ of the form stated in theorem 6.2 and satisfying that they are C^0, that their Fourier series is uniformly convergent.

Finally we observe that, since $\phi^\pm = \phi_0 + \phi_1^\pm$ with $\partial_z \phi_1^\pm \in \mathcal{Z}_{\gamma,\rho}^{\ell+1,\pm}$, then $\partial_z \phi^\pm \in \mathcal{Z}_{\gamma,\rho}^{2r,\pm}$. In particular, we have that $\partial_z \phi^\pm$ is C^0 and the Fourier series of $\phi^\pm$ are uniformly convergent. On the one hand, we notice that since $\phi^\pm$ are analytic with respect to z, $\partial_z \phi^\pm$ and consequently $\mathcal{H}(z, \partial_z \phi^\pm, \tau)$ are C^0 (here we have used that $\mathcal{H}$ is C^q). On the other hand, since $\phi^\pm$ is a solution of the Hamilton–Jacobi equation associated with $\mathcal{H}$, $\partial_\tau \phi^\pm = -\mathcal{H}(z, \partial_z \phi^\pm, \tau)$ and thus $\phi^\pm$ is C^1. An inductive argument allows us to conclude that $\phi^\pm$ is C^{q+1}.

For the second part of theorem 6.2, we follow the same steps as in section 5. We omit the details of the proof because they are quite analogous. section 6 works without any change.

Acknowledgments

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