

# Geometric methods for invariant manifolds in dynamical systems II.

Invariant manifolds associated with hyperbolic fixed points

Maciej Capiński

AGH University of Science and Technology, Kraków

# Plan of the lecture

- Covering relations
- Cone conditions
- Horizontal discs
- Existence of stable manifold
- Existence of unstable manifold
- Intersections of manifolds

## Covering relations

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

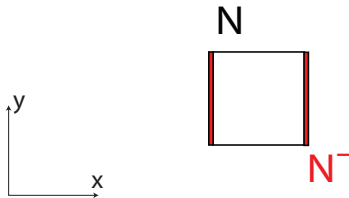
$$N = \overline{B_u} \times \overline{B_s}$$

$$N^- = \partial B_u \times \overline{B_s}$$

### Theorem

If  $N \xrightarrow{F} N$  then  $\exists q^* \in N$

$$F(q^*) = q^*$$



# Covering relations

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

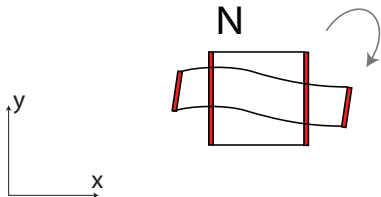
$$N = \overline{B_u} \times \overline{B_s}$$

$$N^- = \partial B_u \times \overline{B_s}$$

## Theorem

If  $N \xrightarrow{F} N$  then  $\exists q^* \in N$

$$F(q^*) = q^*$$



# Covering relations

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

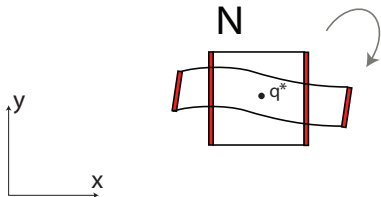
$$N = \overline{B_u} \times \overline{B_s}$$

$$N^- = \partial B_u \times \overline{B_s}$$

## Theorem

If  $N \xrightarrow{F} N$  then  $\exists q^* \in N$

$$F(q^*) = q^*$$



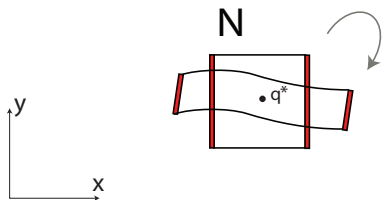
# Covering relations

Our goals

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$N = \overline{B}_u \times \overline{B}_s$$

$$N^- = \partial B_u \times \overline{B}_s$$



## Theorem

If  $N \xrightarrow{F} N$  then  $\exists q \in N$

$$F(q) = q$$

Questions:

- Uniqueness of a fixed point?  
 $F(q^*) = q^*$
- **unstable** manifold?
- **stable** manifold?

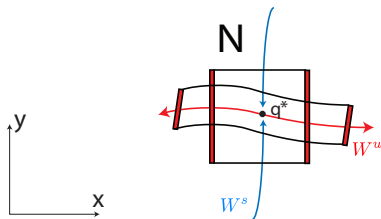
# Covering relations

Our goals

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$N = \overline{B_u} \times \overline{B_s}$$

$$N^- = \partial B_u \times \overline{B_s}$$



## Theorem

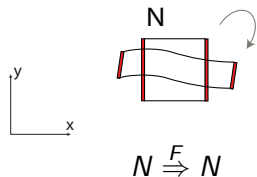
If  $N \xrightarrow{F} N$  then  $\exists q \in N$

$$F(q) = q$$

Questions:

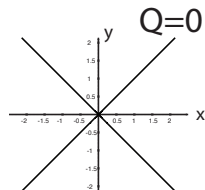
- Uniqueness of a fixed point?  
 $F(q^*) = q^*$
- **unstable** manifold?
- **stable** manifold?

# Cones



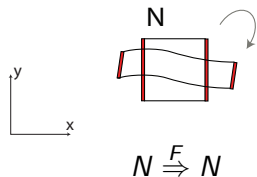
$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$



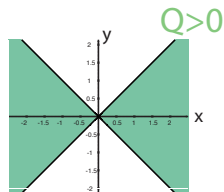


# Cones

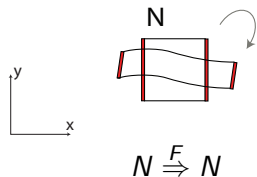


$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$



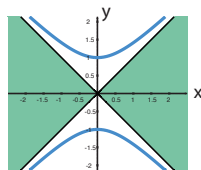
# Cones



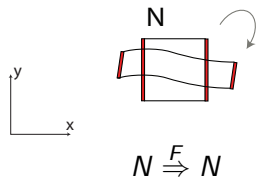
$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

$$Q = b < 0$$



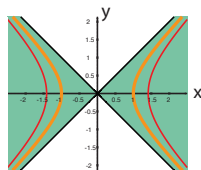
# Cones



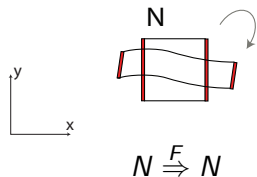
$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

$$Q = a, Q = b, \quad a > b > 0$$



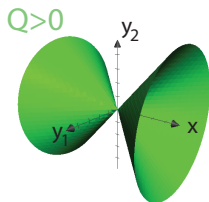
# Cones



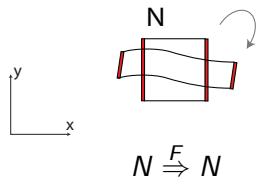
$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

$$u = 1, \quad s = 2$$



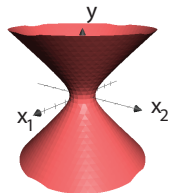
# Cones



$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

$$u = 2, s = 1 \quad Q = a > 0$$

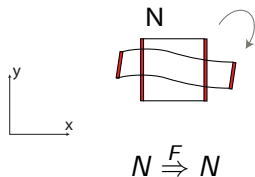


# Cone conditions

$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

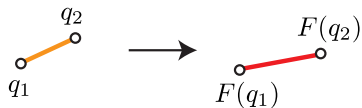
$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$



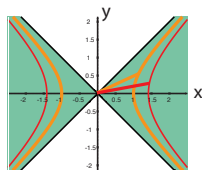
## Definition (forward cone cond.)

$m > 1$ . If  $Q(q_1 - q_2) \geq 0$  then

$$Q(F(q_1) - F(q_2)) > mQ(q_1 - q_2)$$



$$Q = a, Q = b, \quad a > b > 0$$

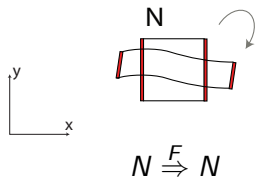


# Cone conditions

$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

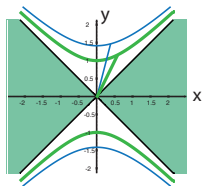
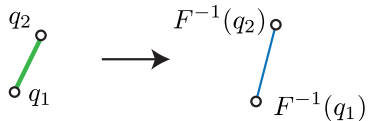


## Definition (backward cone cond.)

$m > 1$ . If  $Q(q_1 - q_2) \leq 0$  then

$$Q(F^{-1}(q_1) - F^{-1}(q_2)) < mQ(q_1 - q_2)$$

$$Q = a, Q = b, \quad a < b < 0$$

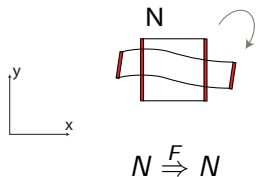


# Cone conditions

$$Q : \mathbb{R}^u \times \mathbb{R}^s \rightarrow \mathbb{R}$$

$$Q(x, y) = \|x\|^2 - \|y\|^2$$

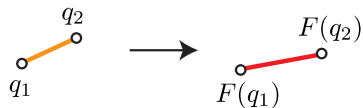
$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$



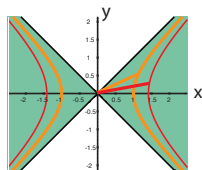
## Definition (forward cone cond.)

$m > 1$ . If  $Q(q_1 - q_2) \geq 0$  then

$$Q(F(q_1) - F(q_2)) > mQ(q_1 - q_2)$$



$$Q = a, Q = b, \quad a > b > 0$$

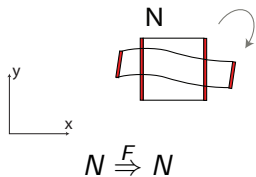




# Our aim: $W^s$

Assumptions:

- Covering:



# Our aim: $W^s$

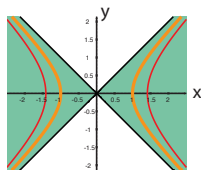
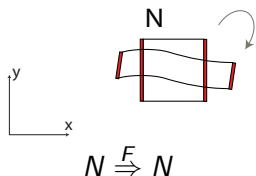
Assumptions:

- Covering:

- Cone conditions:

$m > 1$ . If  $Q(q_1 - q_2) \geq 0$  then

$$Q(F(q_1) - F(q_2)) > mQ(q_1 - q_2)$$



# Our aim: $W^s$

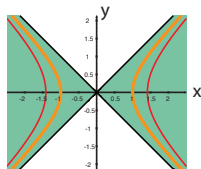
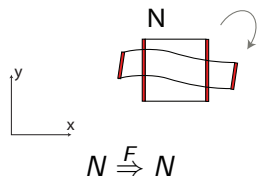
Assumptions:

- Covering:

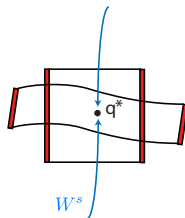
- Cone conditions:

$m > 1$ . If  $Q(q_1 - q_2) \geq 0$  then

$$Q(F(q_1) - F(q_2)) > mQ(q_1 - q_2)$$



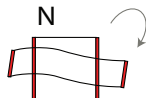
Claim:  $\exists W^s$



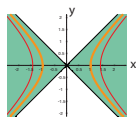
# Horizontal discs

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$N = \overline{B}_u \times \overline{B}_s$$



$$N \xrightarrow{F} N$$



## Definition (horizontal disc)

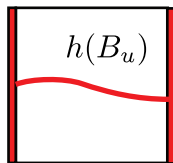
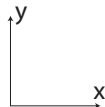
$$h : B_u \rightarrow N$$

- $\pi_x h(x) = x$

cone conditions:

- $x_1 \neq x_2$  then

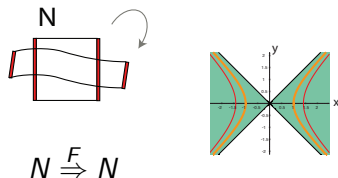
$$Q(h(x_1) - h(x_2)) > 0$$



# Horizontal discs

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$N = \overline{B}_u \times \overline{B}_s$$



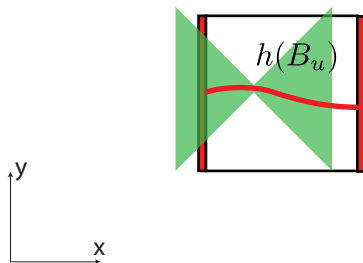
## Definition (horizontal disc)

$$h : B_u \rightarrow N$$

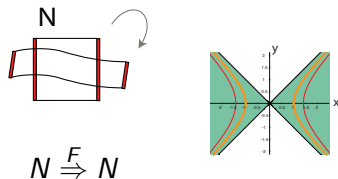
- $\pi_x h(x) = x$

cone conditions:

- $x_1 \neq x_2$  then  
 $Q(h(x_1) - h(x_2)) > 0$



# Horizontal discs



$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

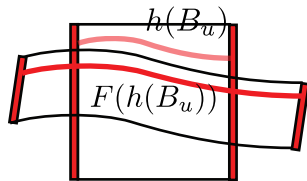
$$N = B_u \times B_s$$

## Lemma

There exists  $h^* : B_u \rightarrow N$

$$F(h(B_u)) \cap N = h^*(B_u)$$

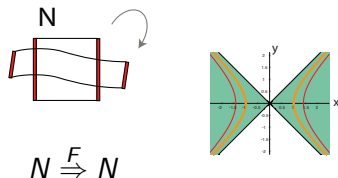
**Proof.** chalk.



# Stable manifold theorem

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$N = B_u \times B_s$$



## Lemma

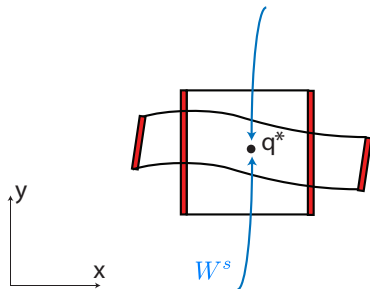
There exists  $h^* : B_u \rightarrow N$

$$F(h(B_u)) \cap N = h^*(B_u)$$

## Theorem

There exists  $W^s$  such that for any  $q \in W^s$

$$F^n(q) \in N \quad n \geq 0$$

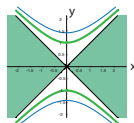
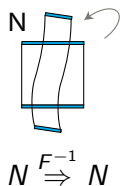


**Proof.** chalk.

# Unstable manifold theorem

$$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$N = B_u \times B_s$$

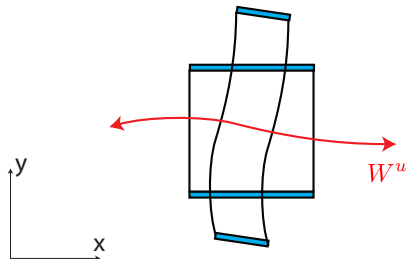


- $F$  invertible.
- $F^{-1}$  satisfies covering and cone conditions.

## Theorem

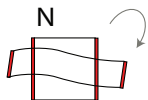
There exists  $W^u$  such that for any  $q \in W^u$

$$F^{-n}(q) \in N \quad n \geq 0$$

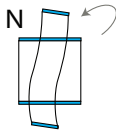
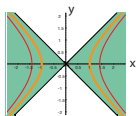




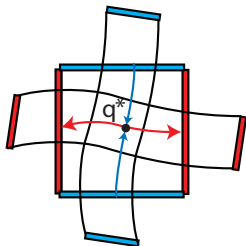
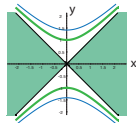
# Summing up



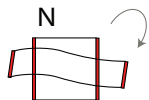
$$N \xrightarrow{F} N$$



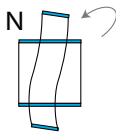
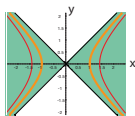
$$N \xrightarrow{F^{-1}} N$$



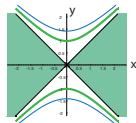
# Summing up



$$N \xrightarrow{F} N$$



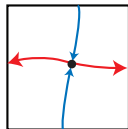
$$N \xrightarrow{F^{-1}} N$$



## Theorem (Brouwer)

If  $f : N \rightarrow N$  is  $C^0$   
then  $\exists q \in N$

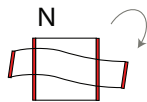
$$f(q) = q$$



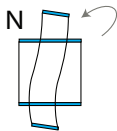
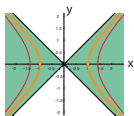
## Exercise:

- horizontal and vertical discs intersect
- $W^u$  is indeed unstable
- $W^s$  is indeed stable

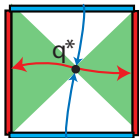
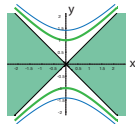
# Tightening bounds



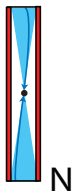
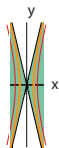
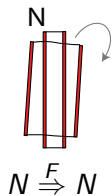
$$N \xrightarrow{F} N$$



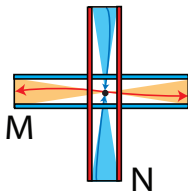
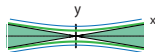
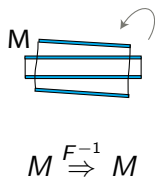
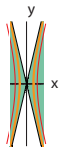
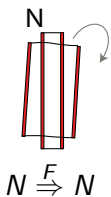
$$N \xrightarrow{F^{-1}} N$$



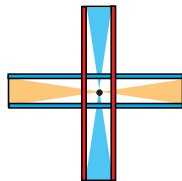
# Tightening bounds



# Tightening bounds



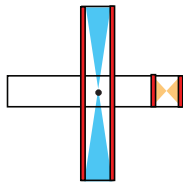
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

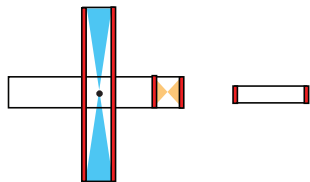
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

# Transversal intersections of manifolds

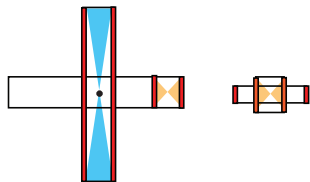


Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*



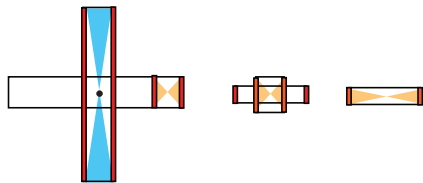
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

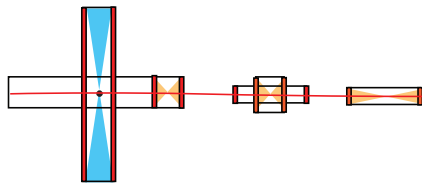
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

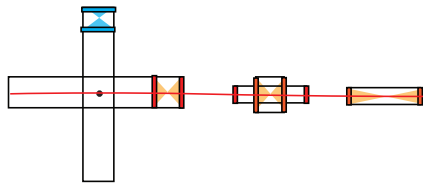
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

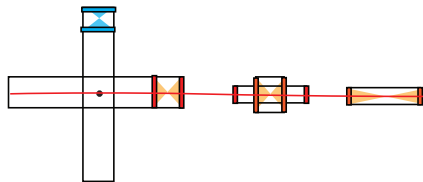
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

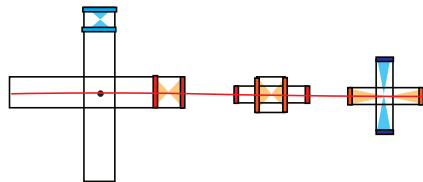
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

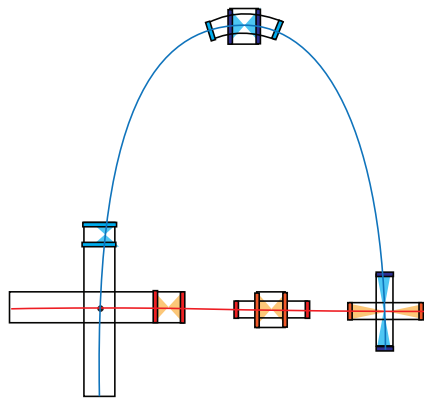
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

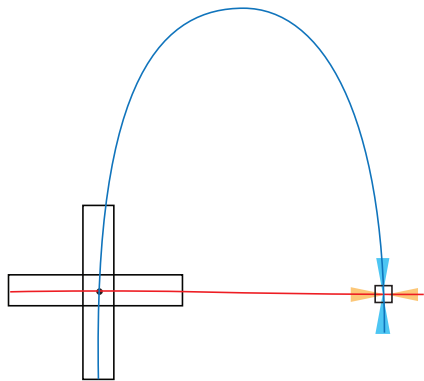
# Transversal intersections of manifolds



Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*

# Transversal intersections of manifolds

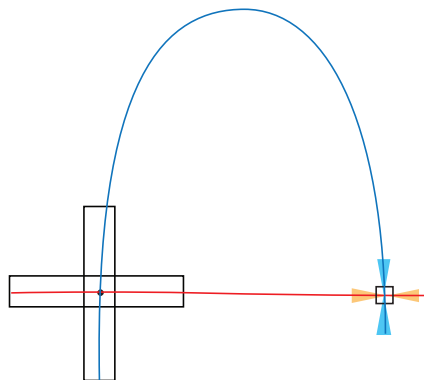


Theorem (Smale-Birkhoff)

*The system has a topological horseshoe (is chaotic).*



## Next lectures



- Not only fixed points
- How to verify the covering condition
- How to verify cone conditions
- Examples

Thank you for your attention

# References

- Covering relations:

[GZ] M. Gidea, P.Zgliczyński, Covering relations for multidimensional dynamical systems I, , J. of Diff. Equations, 202(2004) 32–58

- Stable and unstable manifolds of hyperbolic fixed points:

[Z] P.Zgliczyński, Covering relations, cone conditions and stable manifold theorem , J. of Diff. Equations 246 (2009) 1774–1819